

# A Well-Balanced Multi-Dimensional Reconstruction Scheme for Hydrostatic Equilibria

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Seminar for  
Applied  
Mathematics **SAM**

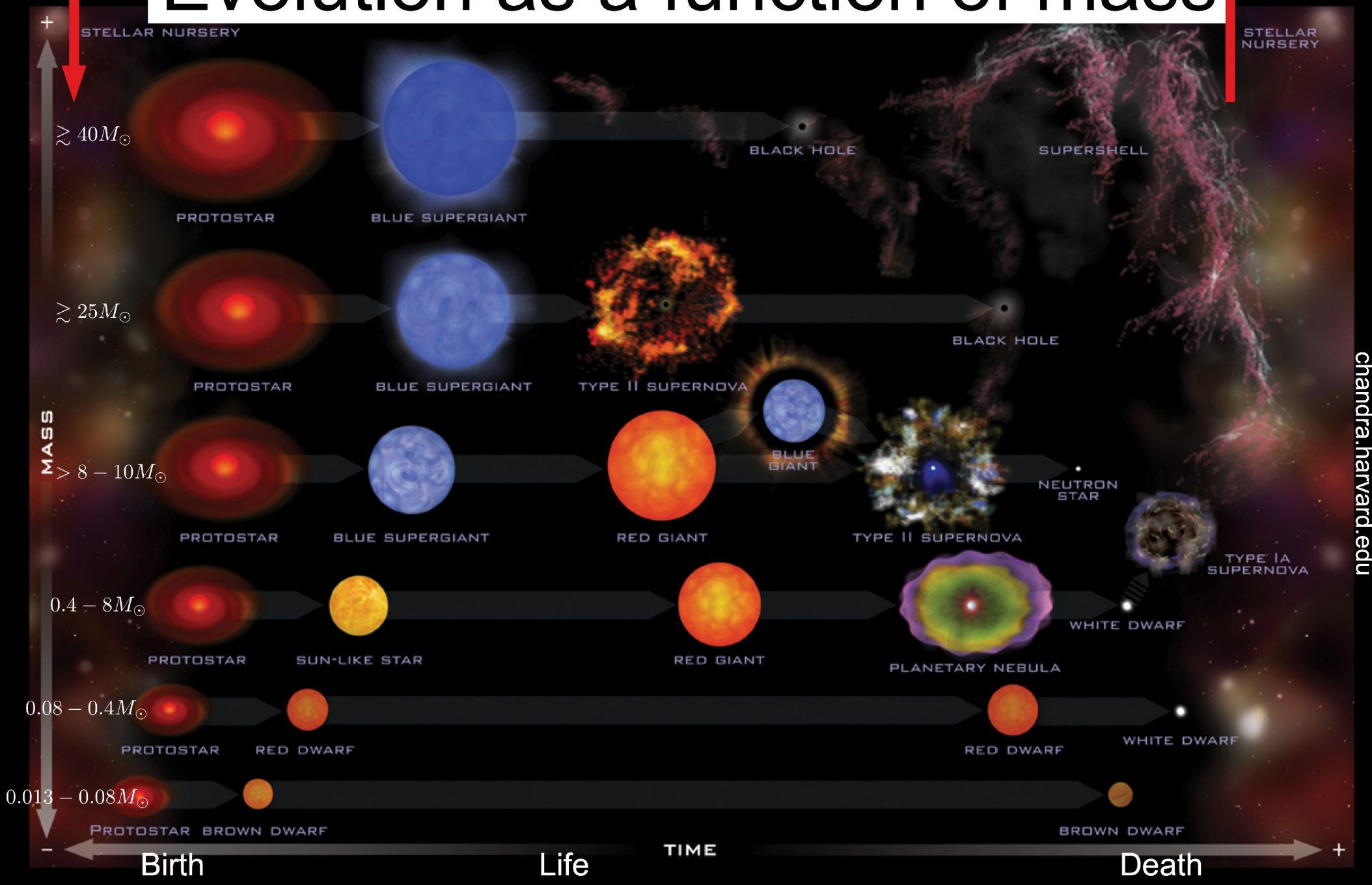


Eidgenössische Technische Hochschule Zürich  
Swiss Federal Institute of Technology Zurich

# Outline

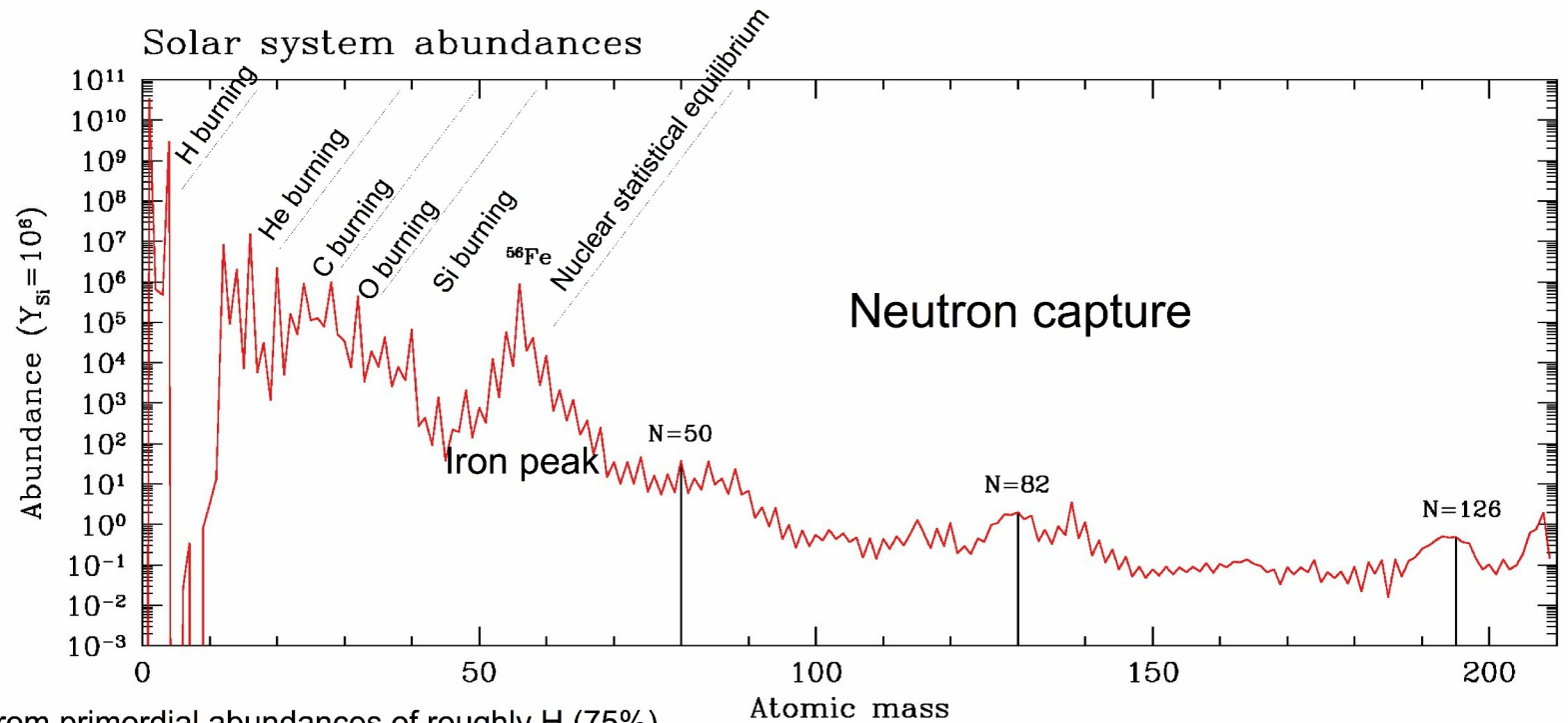
- **Introduction**
  - (Astro)Physical motivation
- **Well-balanced scheme for HydroStatic Equilibrium (HSE)**
  - First order
  - Second order
- **Multi-dimensional extension**
  - Limitations
- **Conclusion**

# Evolution as a function of mass



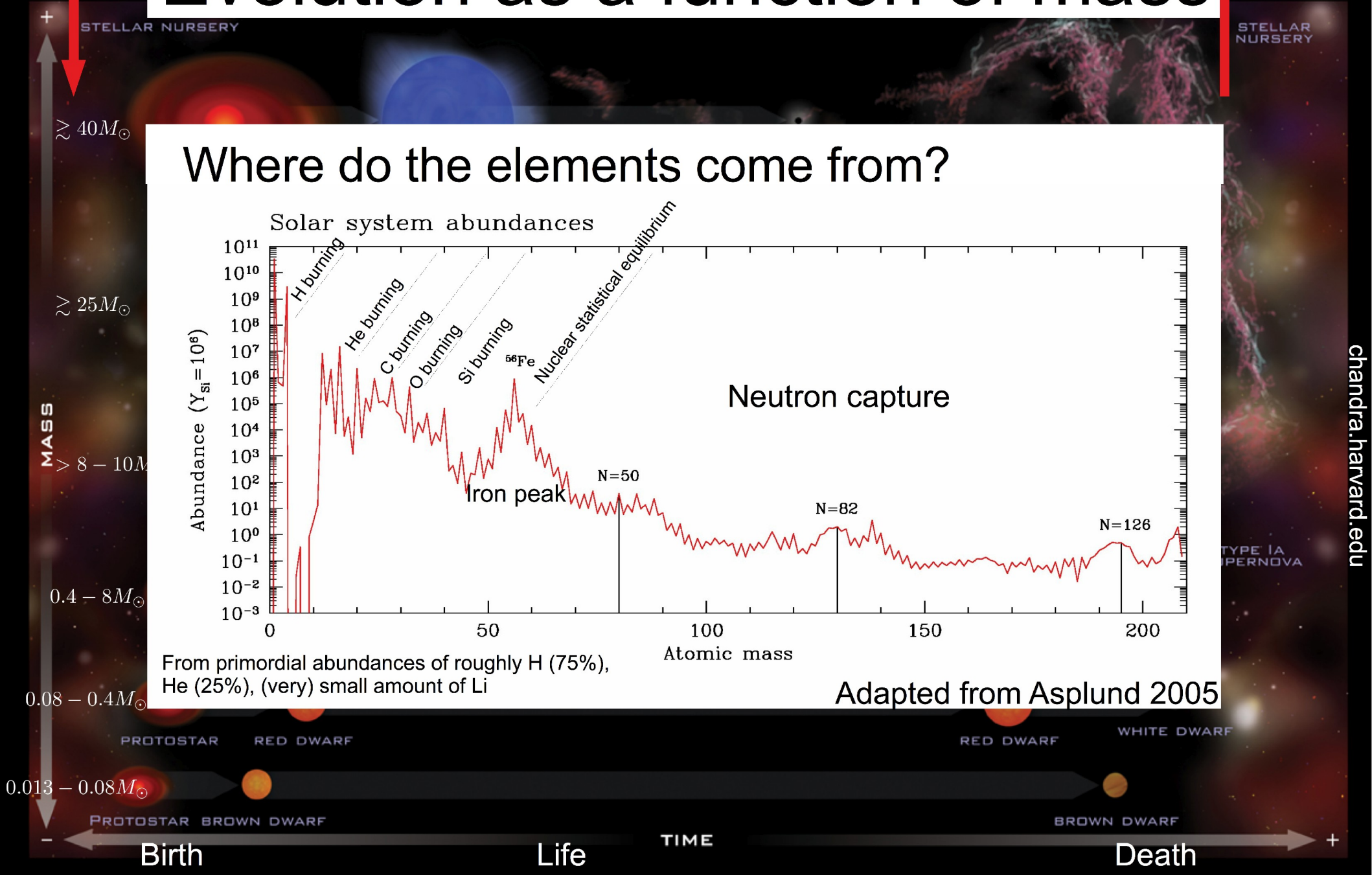
# Evolution as a function of mass

## Where do the elements come from?



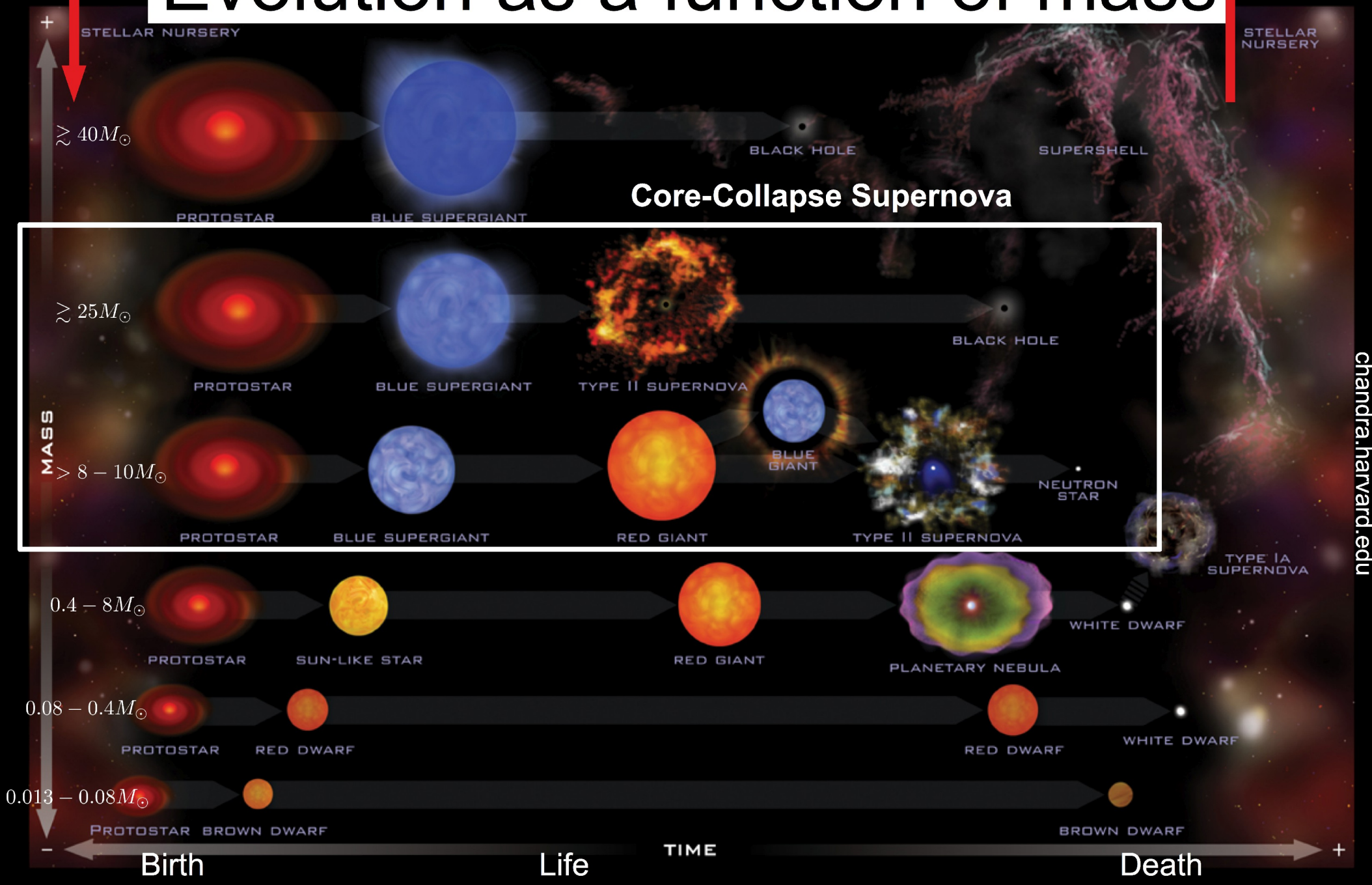
From primordial abundances of roughly H (75%), He (25%), (very) small amount of Li

Adapted from Asplund 2005





# Evolution as a function of mass



# Core-collapse supernova

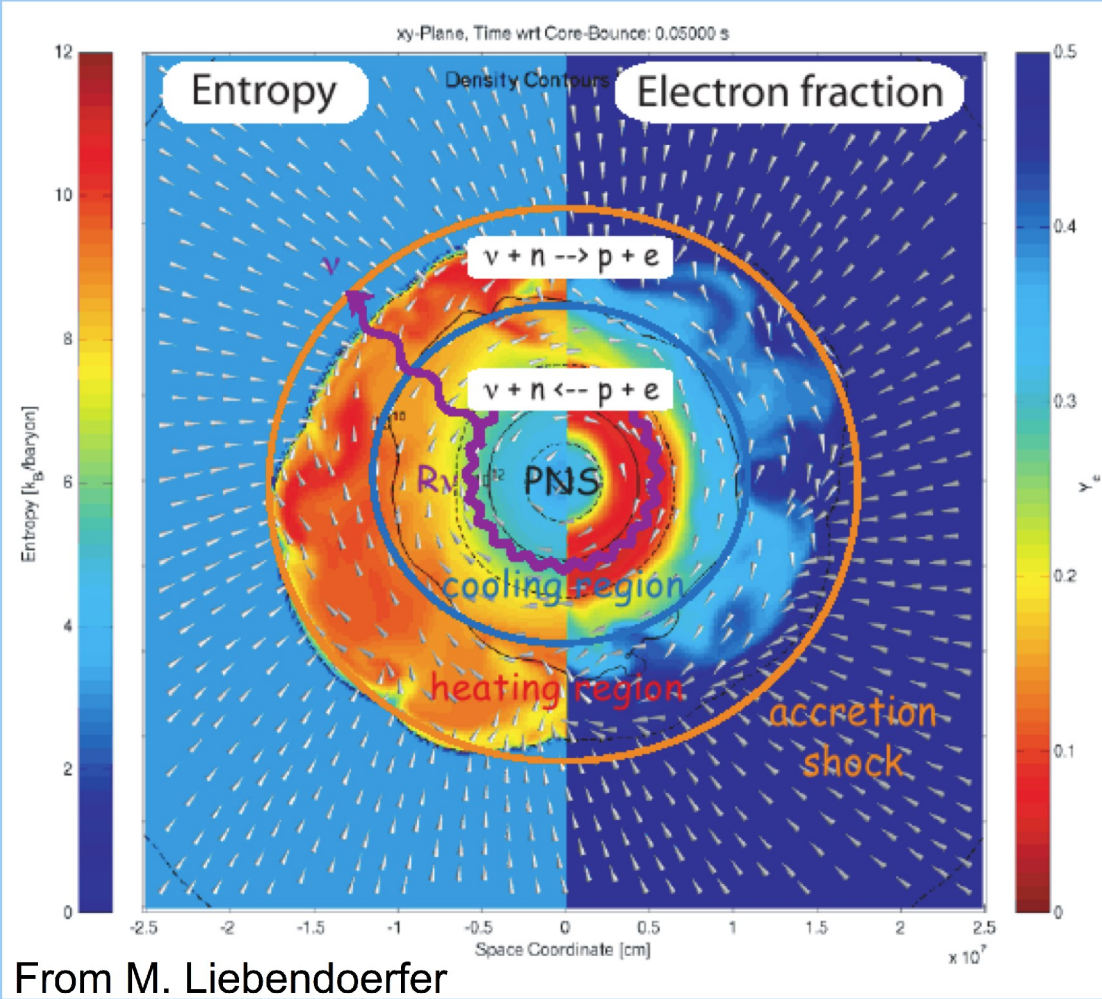
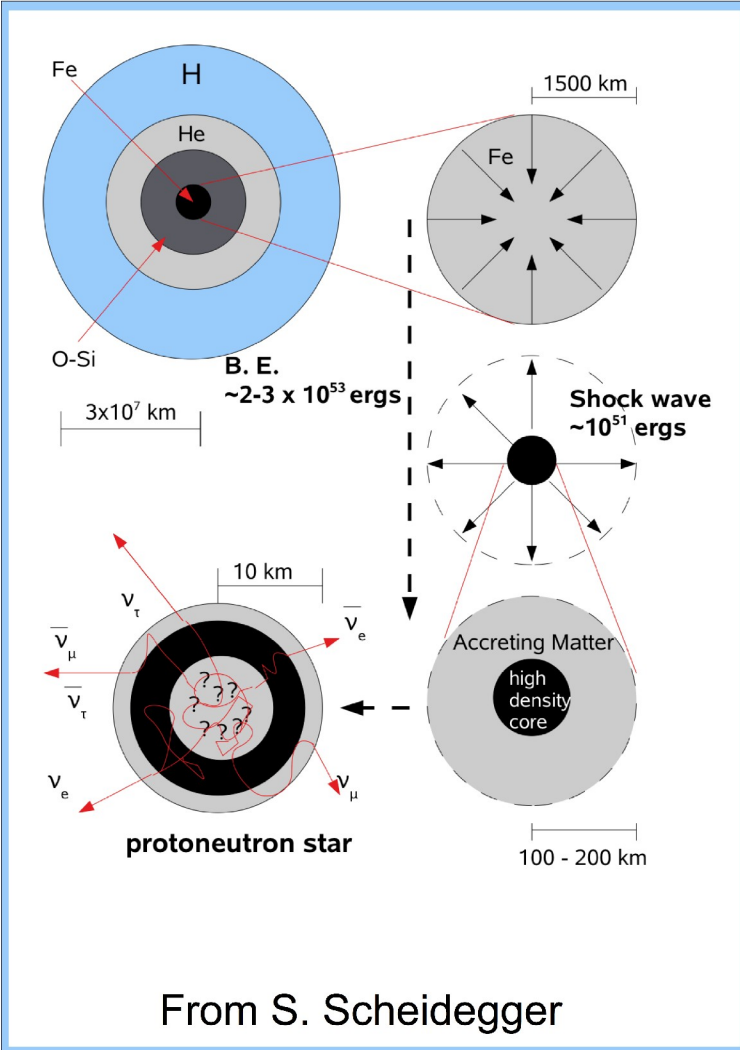
- General idea:
  - Implosion of iron core of massive  $M \gtrsim 8M_{\odot}$  at the end of thermonuclear evolution
  - Explosion powered by gravitational binding energy of forming compact remnant:

$$E_b \approx 3 \times 10^{53} \left( \frac{M}{M_{\odot}} \right)^2 \left( \frac{R}{10\text{km}} \right)^{-1} \text{ erg}$$

**GRAVITY BOMB!**

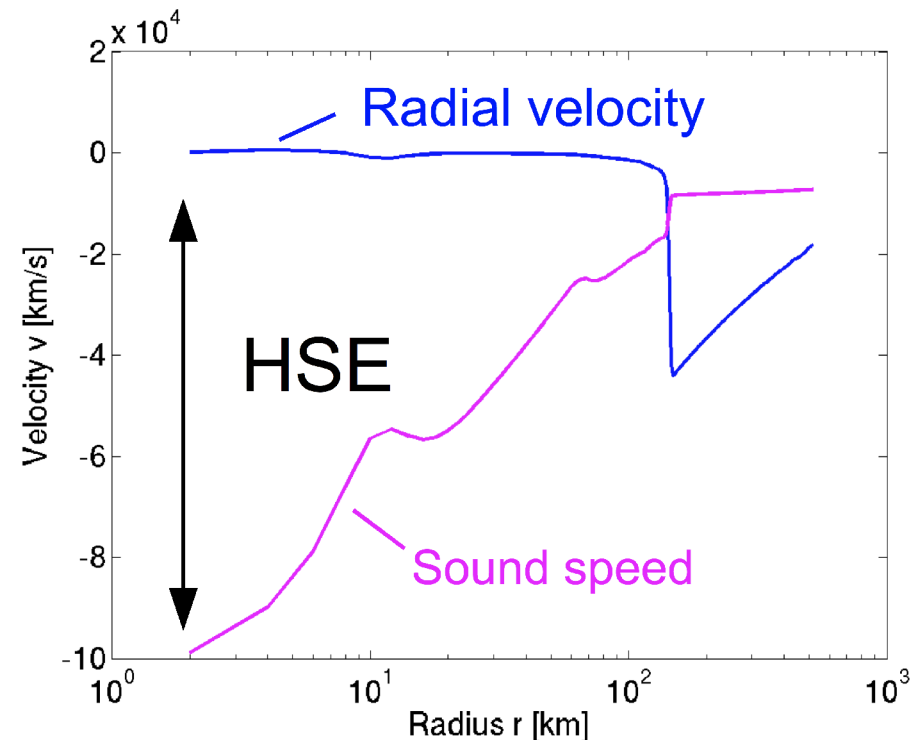
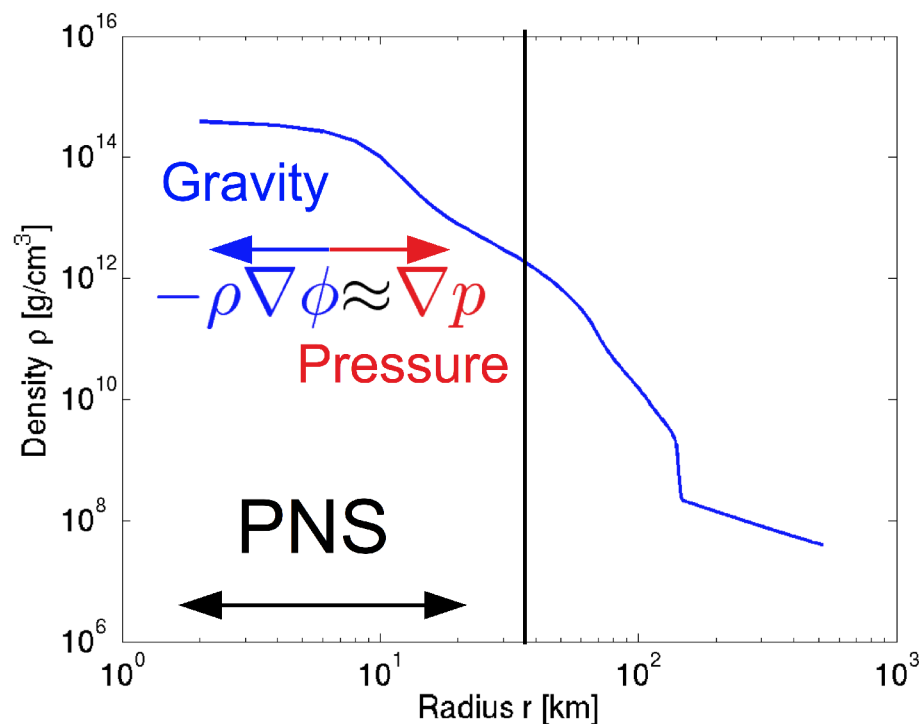
$M$  Mass of remnant  
 $R$  Radius of remnant

# Core-collapse supernova



# Radial profile

- The problem: (in our simulations)



Ability to maintain near hydrostatic equilibrium for a long time!



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# Well-balanced scheme for HSE

- Consider 1D hydrodynamics eqs with gravity

$$\frac{\partial \mathbf{u}}{\partial t} + \frac{\partial \mathbf{F}}{\partial x} = \mathbf{S}$$

$$\mathbf{u} = \begin{bmatrix} \rho \\ \rho v \\ E \end{bmatrix} \quad \mathbf{F} = \begin{bmatrix} \rho v \\ \rho v^2 + p \\ (E + p)v \end{bmatrix} \quad \mathbf{S} = - \begin{bmatrix} 0 \\ \rho \\ \rho v \end{bmatrix} \frac{\partial \phi}{\partial x}$$

- Classical solution algorithm:
  - Solve homogeneous eqs with Godunov type method (i.e. solve Riemann problem)
  - Account for source term in second step (split/unsplit)

# Well-balanced scheme for HSE (2)

- Classical solution algorithm:

$$\mathbf{u}_i^{n+1} = \mathbf{u}_i^n - \frac{\Delta t}{\Delta x} \left( \mathbf{F}_{i+1/2}^n - \mathbf{F}_{i-1/2}^n \right) + \Delta t \mathbf{S}_i^n$$

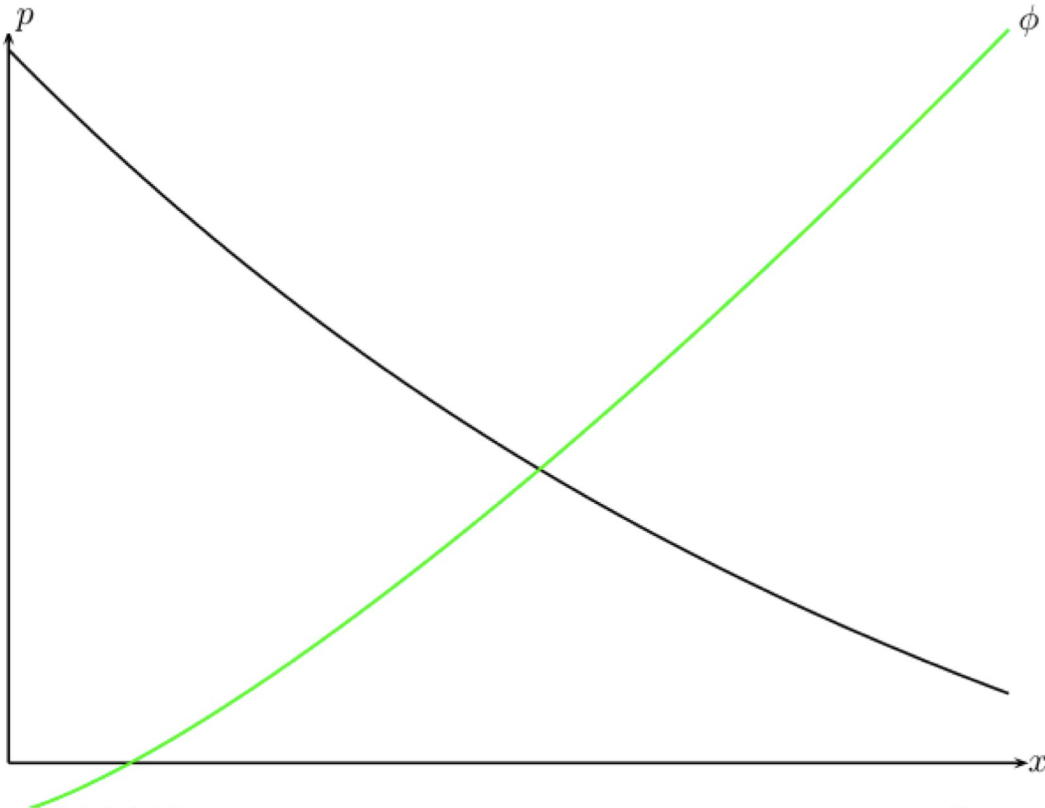
- Numerical flux  $\mathbf{F}_{i\pm 1/2}^n = \mathcal{F}(\mathbf{u}_{i\pm 1/2}^{n,L}, \mathbf{u}_{i\pm 1/2}^{n,R})$   
from (approximate) Riemann solver, e.g.
  - (Local) Lax-Friedrichs Lax (1954), Rusanov (1961)
  - HLL (C) Harten, Lax and van Leer (1983), Toro et al. (1994)
  - Roe Roe (1981)

# Well-balanced scheme for HSE (3)

Interested in hydrostatic equilibrium:

$$\frac{\partial \mathbf{F}}{\partial x} = \mathbf{S} \implies \frac{\partial p}{\partial x} = -\rho \frac{\partial \phi}{\partial x}$$

$$\text{EoS: } p = p(\rho, e)$$

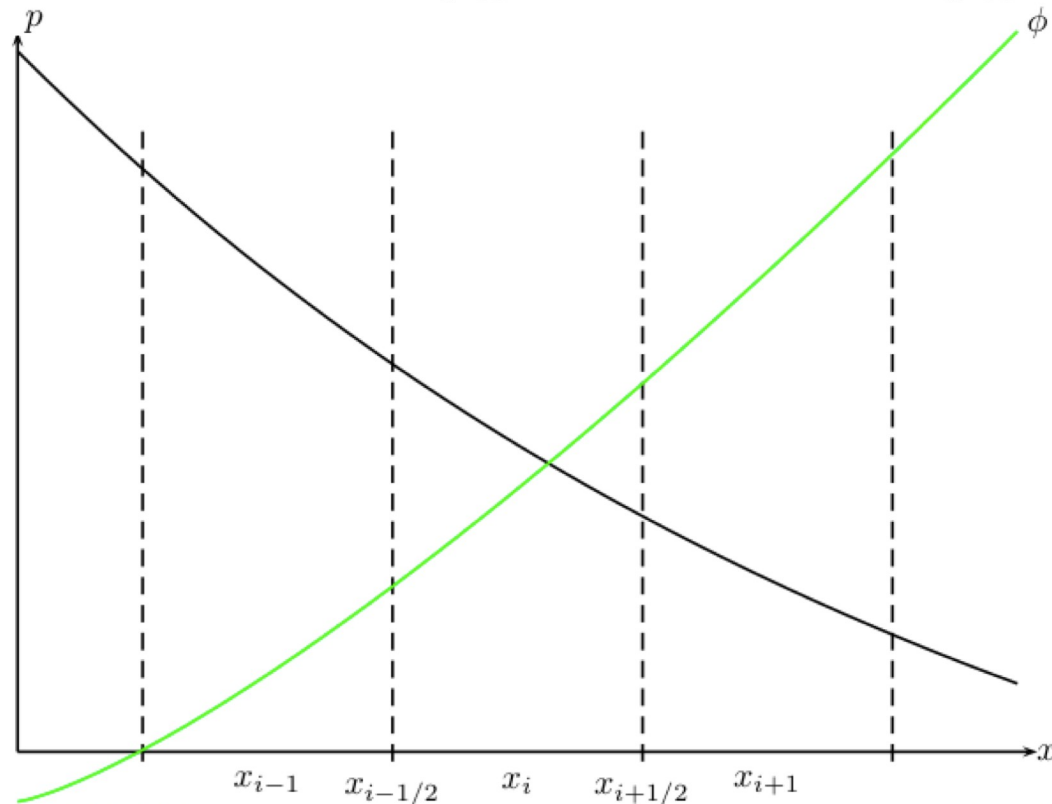




# Well-balanced scheme for HSE (3)

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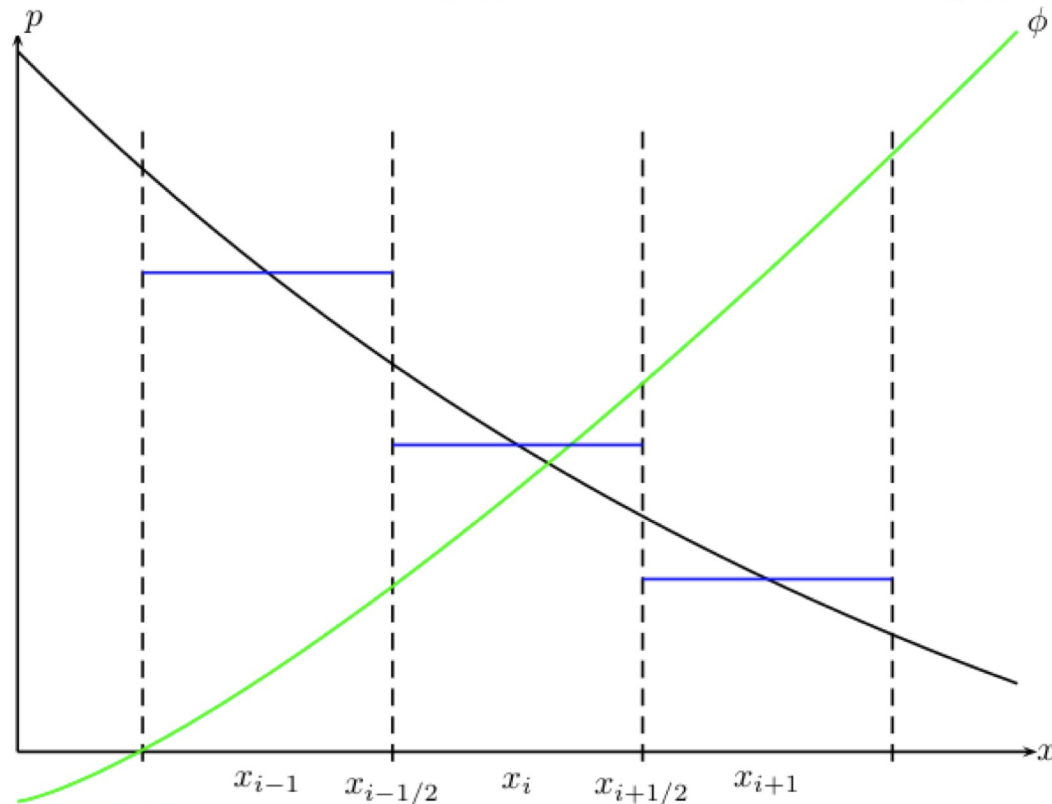


Discretise in cells  $[x_{i-1/2}, x_{i+1/2}]$

# Well-balanced scheme for HSE (3)

Interested in hydrostatic equilibrium:

$$\frac{\partial \mathbf{F}}{\partial x} = \mathbf{S} \implies \frac{\partial p}{\partial x} = -\rho \frac{\partial \phi}{\partial x} \quad \text{EoS: } p = p(\rho, e)$$



Discretise in cells  $[x_{i-1/2}, x_{i+1/2}]$

Define cell averages

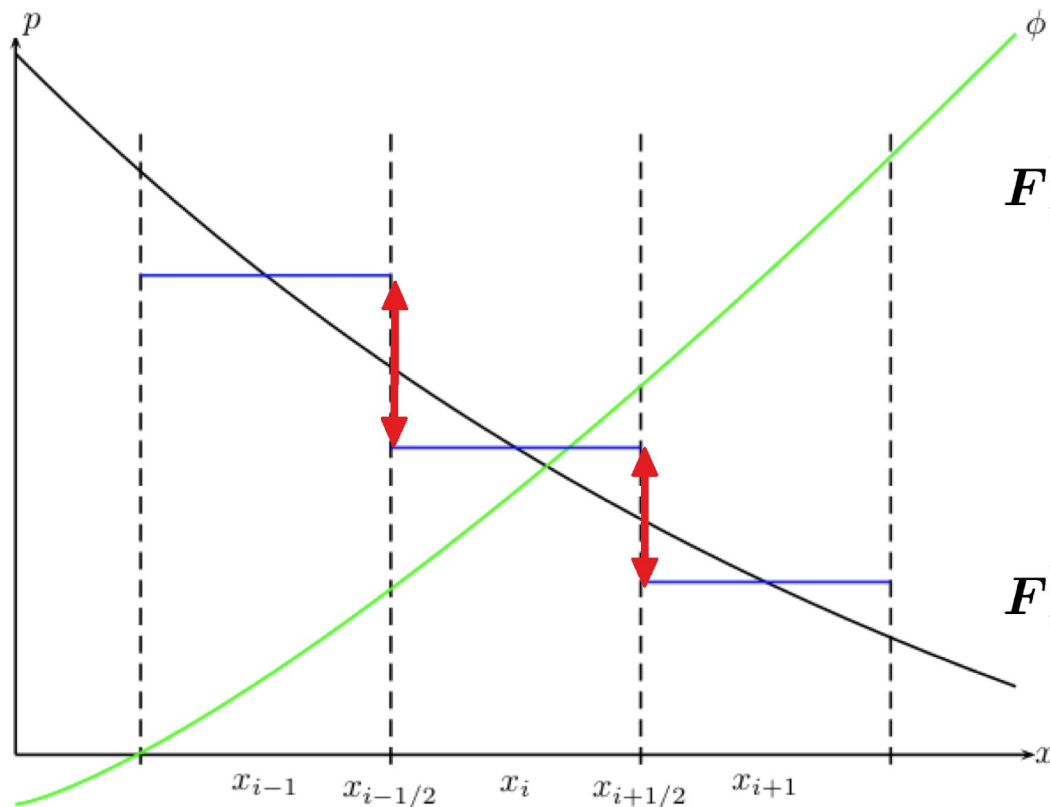
$$\mathbf{u}_i = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \mathbf{u}(x, t^n) dx$$

$$\mathbf{S}_i = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \mathbf{S}(\mathbf{u}(x, t)) dx$$

# Well-balanced scheme for HSE (3)

Interested in hydrostatic equilibrium:

$$\frac{1}{\Delta x} \left( F_{i+1/2}^n - F_{i-1/2}^n \right) \stackrel{?}{=} S_i^n$$



$$F_{i+1/2}^{LxF} = \frac{1}{2} (F_i + F_{i+1}) - \frac{S_{\max}}{2} (u_{i+1} - u_i)$$

**Contains also gravity induced gradient!**

$$F_{i-1/2}^{LxF} = \frac{1}{2} (F_{i-1} + F_i) - \frac{S_{\max}}{2} (u_i - u_{i-1})$$

# Well-balanced scheme for HSE (3)

Inter  
equil

Hydrostatic atmosphere in a constant gravitational field

$$\phi(x) = gx \quad \rho(x) = \left[ \rho_0^{\gamma-1} - \frac{g}{K} \frac{\gamma-1}{\gamma} x \right]^{\frac{1}{\gamma-1}} \quad p = \frac{p_0}{\rho_0^\gamma} \rho^\gamma = K \rho^\gamma$$

$$x \in [0, 2]$$

Error in pressure:  
(after 2 sound  
crossing times)

N	1st	2ndTVD
32	9.3E-02	1.3E-03
64	4.6E-02	3.2E-04
128	2.3E-02	8.0E-05
256	1.2E-02	2.0E-05
512	5.7E-03	5.1E-06

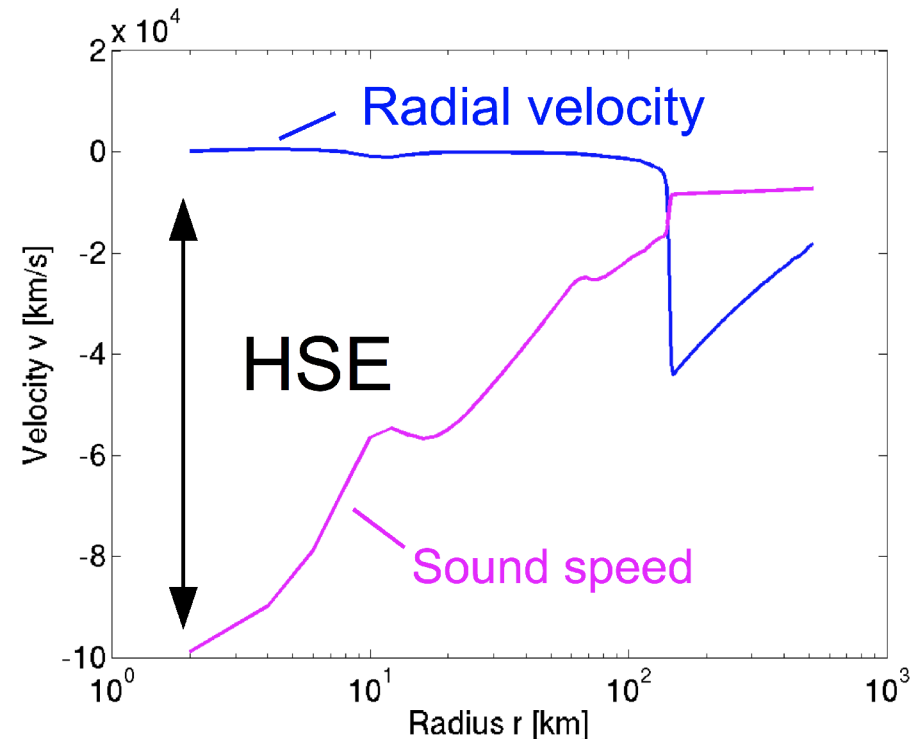
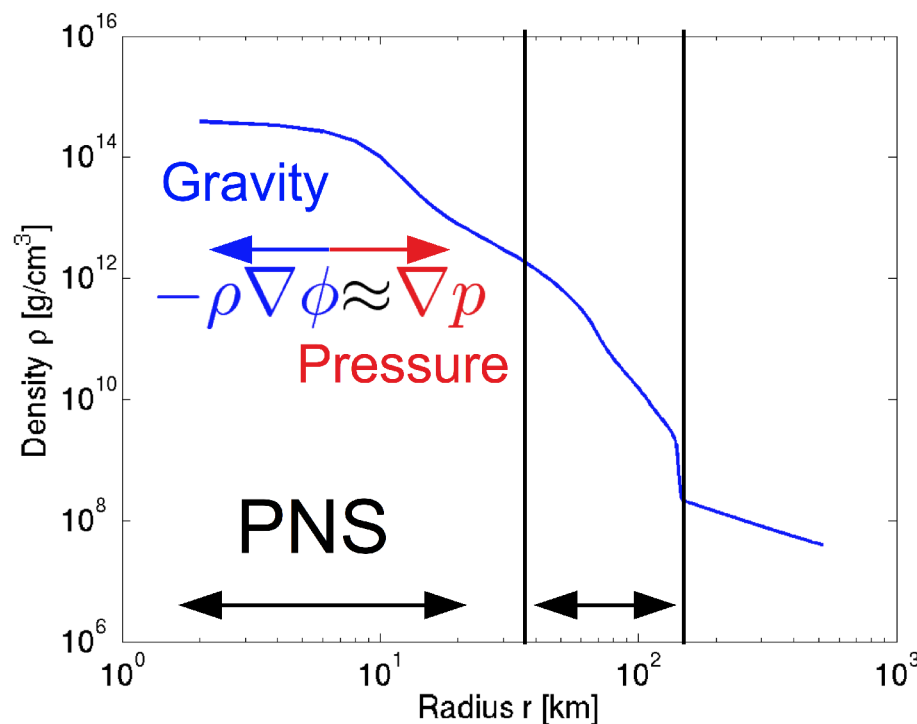
$$Err = \frac{1}{N} \sum_i |p_i - p_i^0|$$

HLLC numerical flux



# Well-balanced scheme for HSE (4)

- The problem: (in our simulations)



Ability to maintain near hydrostatic equilibrium for a long time!

# Well-balanced scheme for HSE (5)

- Solutions:
  - Define a **global** stationary state  $u_0(r)$  **at each time step** and evolve  $u(\boldsymbol{x}) - u_0(r)$
  - Steady state preserving reconstructions, well-balanced schemes e.g. LeVeque (1998), LeVeque & Bale (1998), Botta et al. (2004), Fuchs et al. (2010)

Note: there are many, many more... especially for shallow-water eqs!!!

# Well-balanced scheme for HSE (5)

- Solutions:

- Define a **global** stationary state  $u_0(r)$  **at each time step** and evolve  $u(\boldsymbol{x}) - u_0(r)$
  - Steady state preserving reconstructions, well-balanced schemes
- e.g. LeVeque (1998), LeVeque & Bale (1998), Botta et al. (2004), Fuchs et al. (2010)

## Requirements

- Equilibrium not known in advance (self-gravity)
- Extensible for general EoS
- (At least) second order accuracy

# Well-balanced scheme for HSE (6)

Interested in **numerical** hydrostatic equilibrium:

$$\frac{1}{\Delta x} \left( \mathbf{F}_{i+1/2}^n - \mathbf{F}_{i-1/2}^n \right) = \mathbf{S}_i^n$$

$$\frac{\partial p}{\partial x} + O(\Delta x^2) = \frac{p_{i+1/2} - p_{i-1/2}}{\Delta x} = -\rho_i \frac{\phi_{i+1} - \phi_{i-1}}{2\Delta x} = -\rho \frac{\partial \phi}{\partial x} + O(\Delta x^2)$$

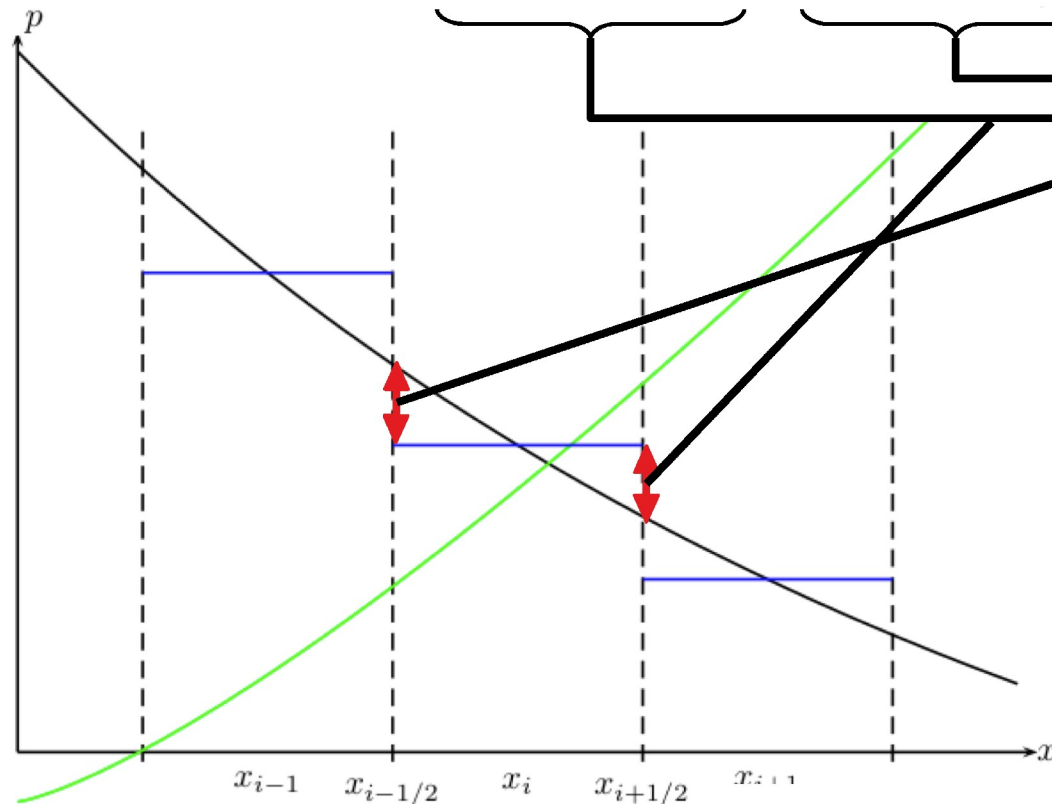
$$\frac{(p_{i+1/2} - p_i) - (p_{i-1/2} - p_i)}{\Delta x} = -\frac{\rho_i}{2} \frac{(\phi_{i+1} - \phi_i) - (\phi_{i-1} - \phi_i)}{\Delta x}$$



# Well-balanced scheme for HSE (6)

Interested in **numerical** hydrostatic equilibrium:

$$\underbrace{\frac{p_{i+1/2} - p_i}{\Delta x}}_{\text{left}} - \underbrace{\frac{p_{i-1/2} - p_i}{\Delta x}}_{\text{right}} = -\frac{\rho_i}{2} \left( \underbrace{\frac{\phi_{i+1} - \phi_i}{\Delta x}}_{\text{left}} - \underbrace{\frac{\phi_{i-1} - \phi_i}{\Delta x}}_{\text{right}} \right)$$



Equilibrium reconstruction:

$$p_{i+1/2} = p_i + \frac{\Delta x}{2} \Delta p_i^+$$

$$p_{i-1/2} = p_i - \frac{\Delta x}{2} \Delta p_i^-$$

Equilibrium differences:

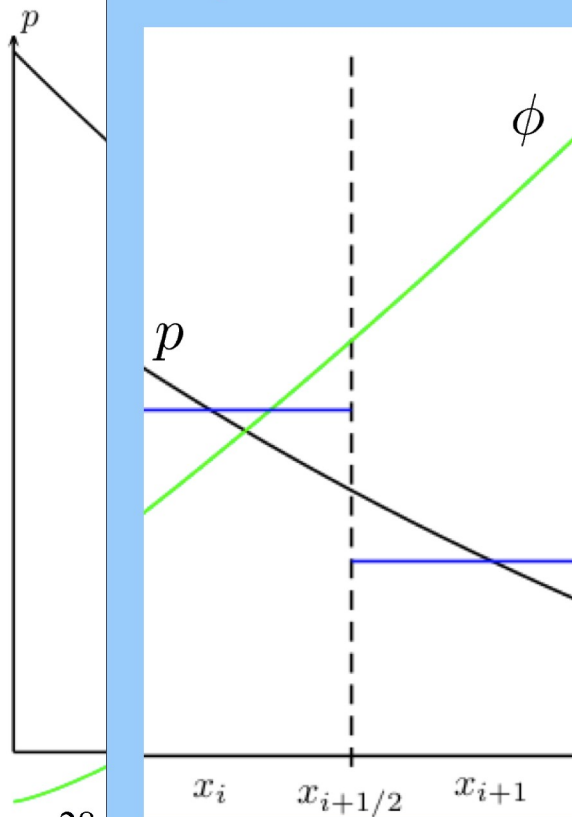
$$\Delta p_i^+ = -\rho_i \frac{\phi_{i+1} - \phi_i}{\Delta x}$$

$$\Delta p_i^- = -\rho_i \frac{\phi_i - \phi_{i-1}}{\Delta x}$$

# Well-balanced scheme for HSE (6)

Interested in **numerical** hydrostatic equilibrium:

Equilibrium?



$$p_{i+1/2}^L \neq p_{i+1/2}^R$$

$$p_i + \frac{\Delta x}{2} \Delta p_i^+ = p_{i+1} - \frac{\Delta x}{2} \Delta p_{i+1}^-$$

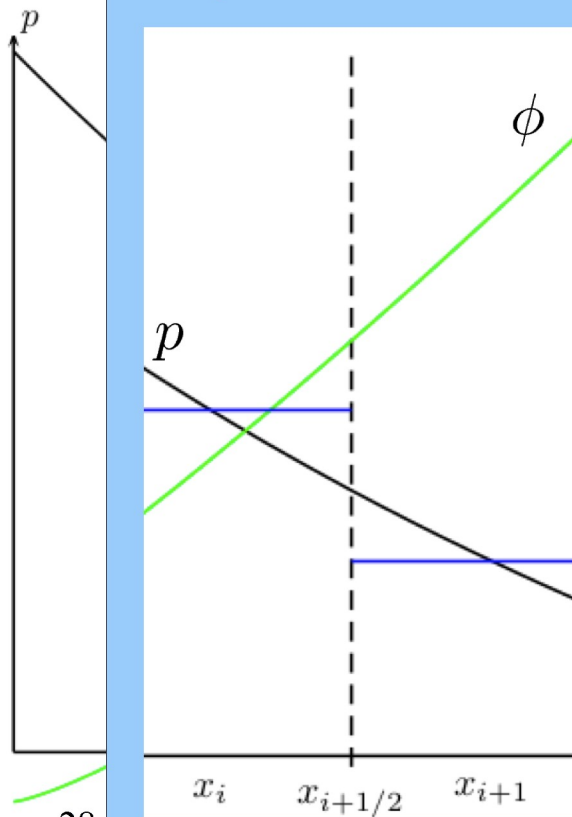
$$\frac{p_{i+1} - p_i}{\Delta x} = - \frac{\rho_i + \rho_{i+1}}{2} \frac{\phi_{i+1} - \phi_i}{\Delta x}$$

**Discrete HydroStatic Equilibrium**

# Well-balanced scheme for HSE (6)

Interested in **numerical** hydrostatic equilibrium:

Equilibrium?



$$p_{i+1/2}^L \stackrel{!}{=} p_{i+1/2}^R$$

Requirement on Riemann solver:

$$F_{i\pm 1/2}^n = \mathcal{F}\left(\begin{bmatrix} \rho_{i+1/2}^L \\ 0 \\ p_{i+1/2} \end{bmatrix}, \begin{bmatrix} \rho_{i+1/2}^R \\ 0 \\ p_{i+1/2} \end{bmatrix}\right) = \begin{bmatrix} 0 \\ p_{i+1/2} \\ 0 \end{bmatrix}$$

e.g. HLLC, Roe

**Discrete HydroStatic Equilibrium**

# Well-balanced scheme for HSE (7)

- Second order extension:

$$\tilde{\sigma}_i = \varphi \left( \frac{u_i - u_{i-1}}{\Delta x} - \frac{\Delta u_{i-1}^+ + \Delta u_i^-}{2}, \frac{u_{i+1} - u_i}{\Delta x} - \frac{\Delta u_i^+ + \Delta u_{i+1}^-}{2} \right)$$

$$u_{i+1/2}^L = u_i + \left( \Delta u_i^+ + \tilde{\sigma}_i \right) \frac{\Delta x}{2}$$

$$u_{i+1/2}^R = u_{i+1} - \left( \Delta u_{i+1}^- - \tilde{\sigma}_{i+1} \right) \frac{\Delta x}{2}$$

$$\Delta u_i^\pm = \begin{bmatrix} 0 \\ 0 \\ \frac{\Delta p_i^\pm}{\gamma - 1} \end{bmatrix}$$

## Reconstruction in deviation from equilibrium

Similar to Botta et al. 2004, Fuchs et al. 2010

- Time stepping:
 
$$u^* = u^n + \Delta t^n \mathbf{L}(u^n)$$

$$u^{**} = u^* + \Delta t^n \mathbf{L}(u^*)$$

$$u^{n+1} = \frac{1}{2} (u^n + u^{**})$$

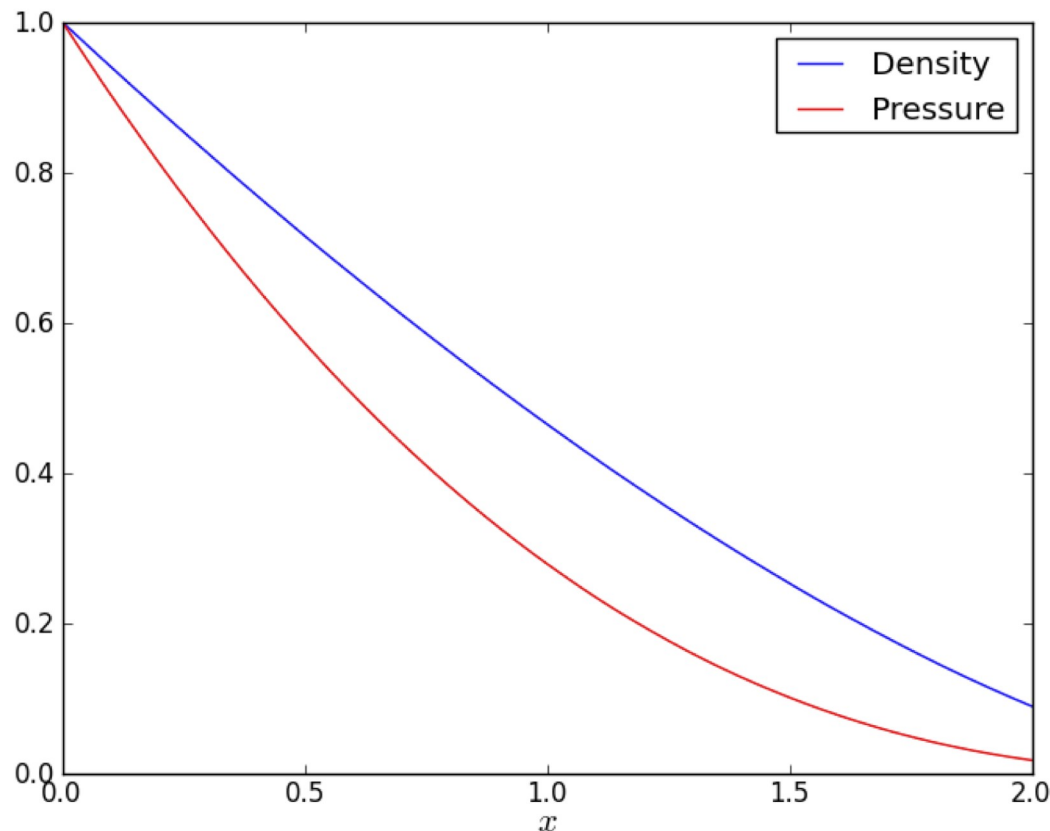
Strong Stability Preserving  
Runge-Kutta,  
Gottlieb et al. 2001

# Example 1

Hydrostatic atmosphere in a constant gravitational field

$$\phi_i = gx_i \quad \frac{p_{i+1} - p_i}{\Delta x} = -\frac{\rho_i + \rho_{i+1}}{2} \frac{\phi_{i+1} - \phi_i}{\Delta x} \quad p_i = K_i \rho_i^\gamma$$

$$x \in [0, 2] \quad K = \text{const.} \quad \sim \text{entropy}$$



Error in pressure:

N	1st	2ndTVD
32	9.3E-02 / <b>4.0E-16</b>	1.3E-03 / <b>2.0E-16</b>
64	4.6E-02 / <b>2.2E-15</b>	3.2E-04 / <b>8.7E-17</b>
128	2.3E-02 / <b>2.9E-15</b>	8.0E-05 / <b>8.1E-16</b>
256	1.2E-02 / <b>2.9E-15</b>	2.0E-05 / <b>3.8E-16</b>
512	5.7E-03 / <b>8.1E-14</b>	5.1E-06 / <b>1.8E-15</b>

$$Err = \frac{1}{N} \sum_i |p_i - p_i^0|$$

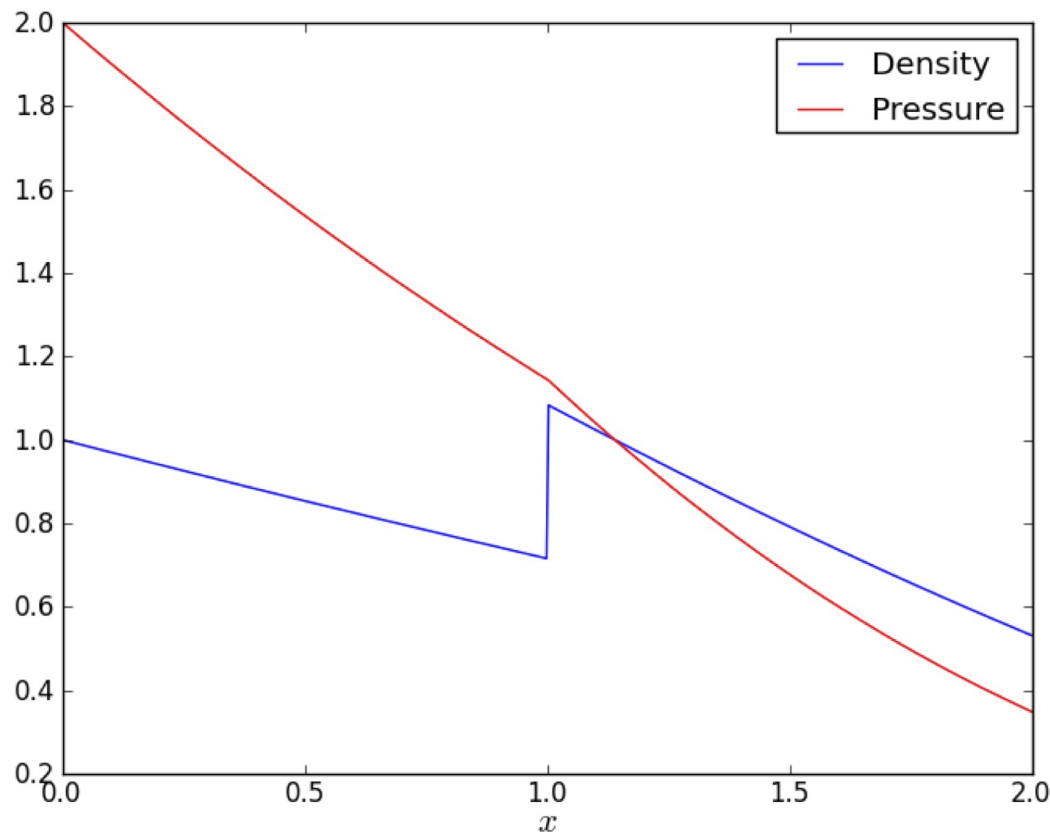
# Example 2

Hydrostatic atmosphere in a constant gravitational field

$$\phi_i = gx_i \quad \frac{p_{i+1} - p_i}{\Delta x} = -\frac{\rho_i + \rho_{i+1}}{2} \frac{\phi_{i+1} - \phi_i}{\Delta x} \quad p_i = K_i \rho_i^\gamma$$

$$x \in [0, 2]$$

$$K = \begin{cases} 2 & \text{if } x < 1 \\ 1 & \text{if } x \geq 1 \end{cases} \sim \text{entropy}$$



Error in pressure:

N	1st	2ndTVD
32	6.3E-02 / <b>3.3E-16</b>	6.2E-04 / <b>1.3E-16</b>
64	3.2E-02 / <b>3.8E-15</b>	1.6E-04 / <b>4.6E-16</b>
128	1.6E-02 / <b>6.1E-15</b>	4.2E-05 / <b>8.8E-16</b>
256	8.0E-03 / <b>7.0E-15</b>	1.1E-05 / <b>6.7E-16</b>
512	4.0E-03 / <b>1.1E-13</b>	2.7E-06 / <b>3.4E-15</b>

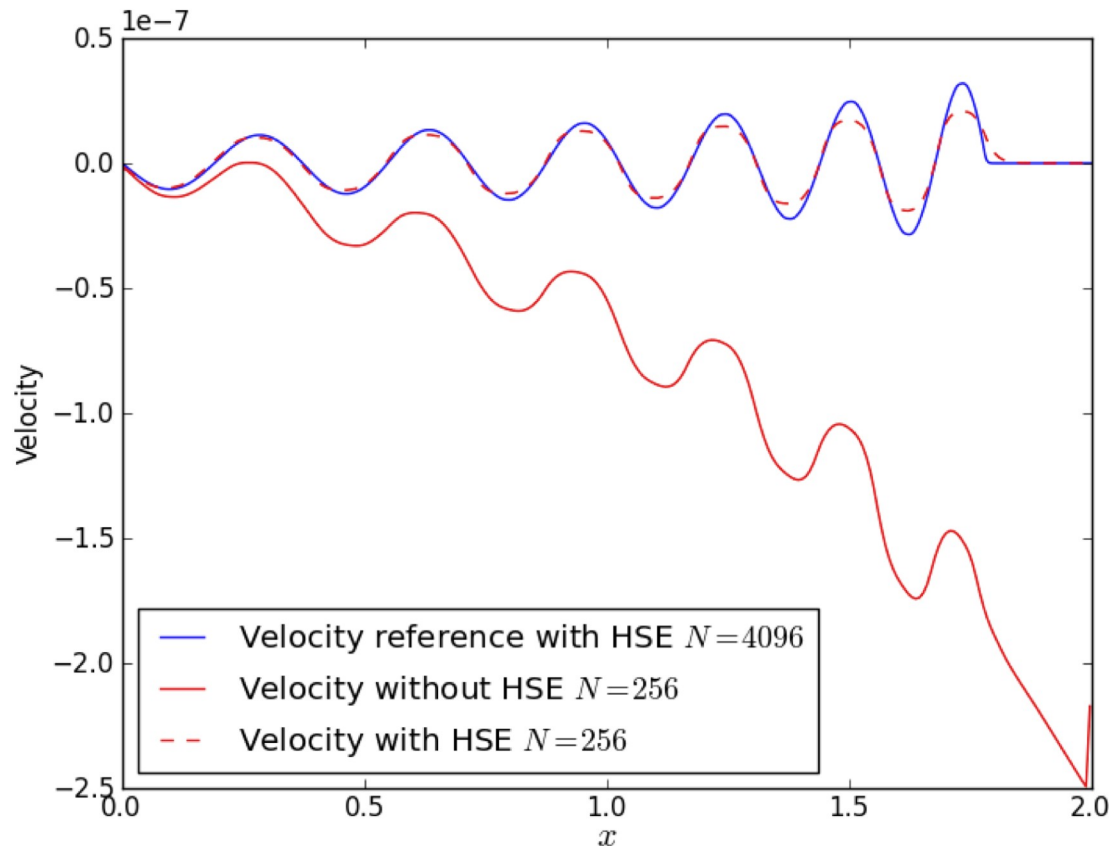
$$Err = \frac{1}{N} \sum_i |p_i - p_i^0|$$



# Example 3

Hydrostatic atmosphere in a constant gravitational field  
+ **small** amplitude waves

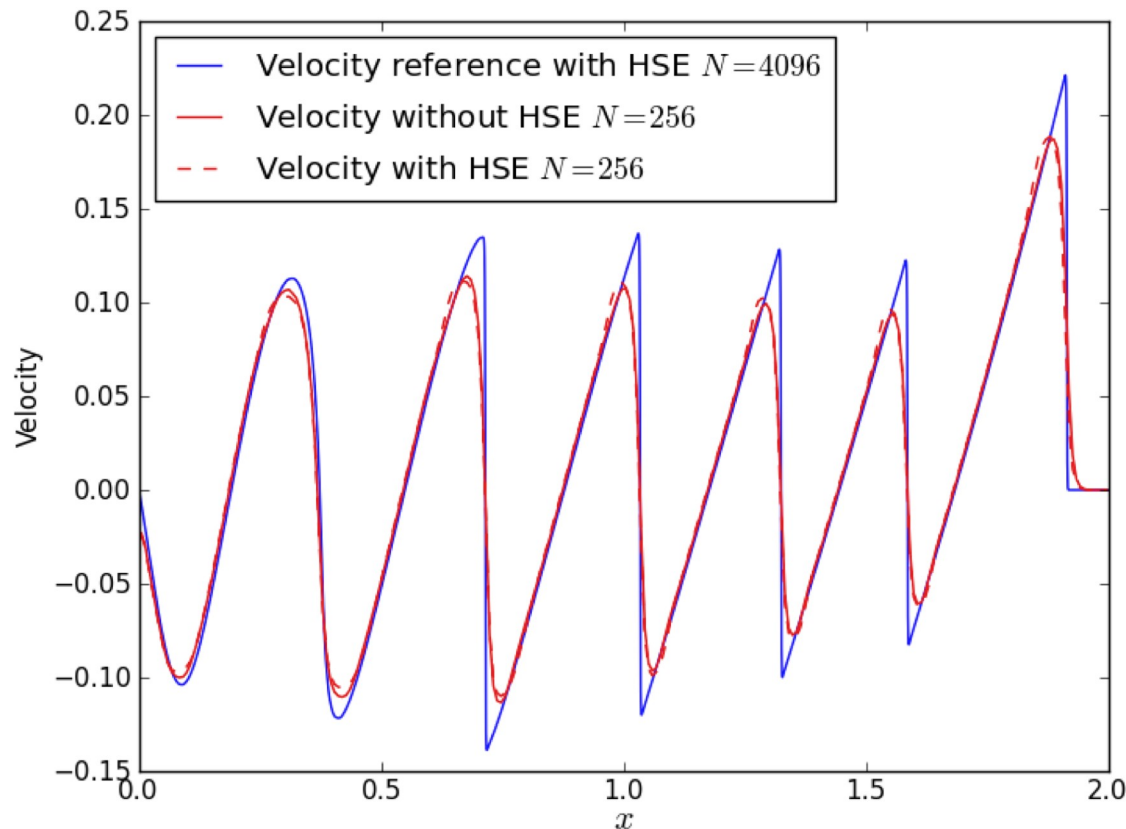
Velocity perturbation:  $v(t, x = 0) = 10^{-8} \sin\left(\frac{6}{1.8} 2\pi t\right)$



## Example 3 (2)

Hydrostatic atmosphere in a constant gravitational field  
+ **large** amplitude waves

Velocity perturbation:  $v(t, x = 0) = 10^{-1} \sin\left(\frac{6}{1.8} 2\pi t\right)$



# Example 6

Polytrope: model star (e.g. main sequence stars, white dwarfs, neutron stars)

Euler equations in spherical symmetry:

$$\frac{\partial(\textcolor{red}{r}^2 \mathbf{u})}{\partial t} + \frac{\partial(\textcolor{red}{r}^2 \mathbf{F})}{\partial r} = \textcolor{red}{r}^2 \mathbf{S}$$

$$\mathbf{u} = \begin{bmatrix} \rho \\ \rho v \\ E \end{bmatrix} \quad \mathbf{F} = \begin{bmatrix} \rho v \\ \rho v^2 + p \\ (E + p)v \end{bmatrix} \quad \mathbf{S} = \frac{\textcolor{red}{2}p}{\textcolor{red}{r}} - \begin{bmatrix} 0 \\ \rho \\ \rho v \end{bmatrix} \frac{\partial \phi}{\partial x}$$

Poisson equation in spherical symmetry:

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \phi}{\partial r} \right) = 4\pi G \rho$$

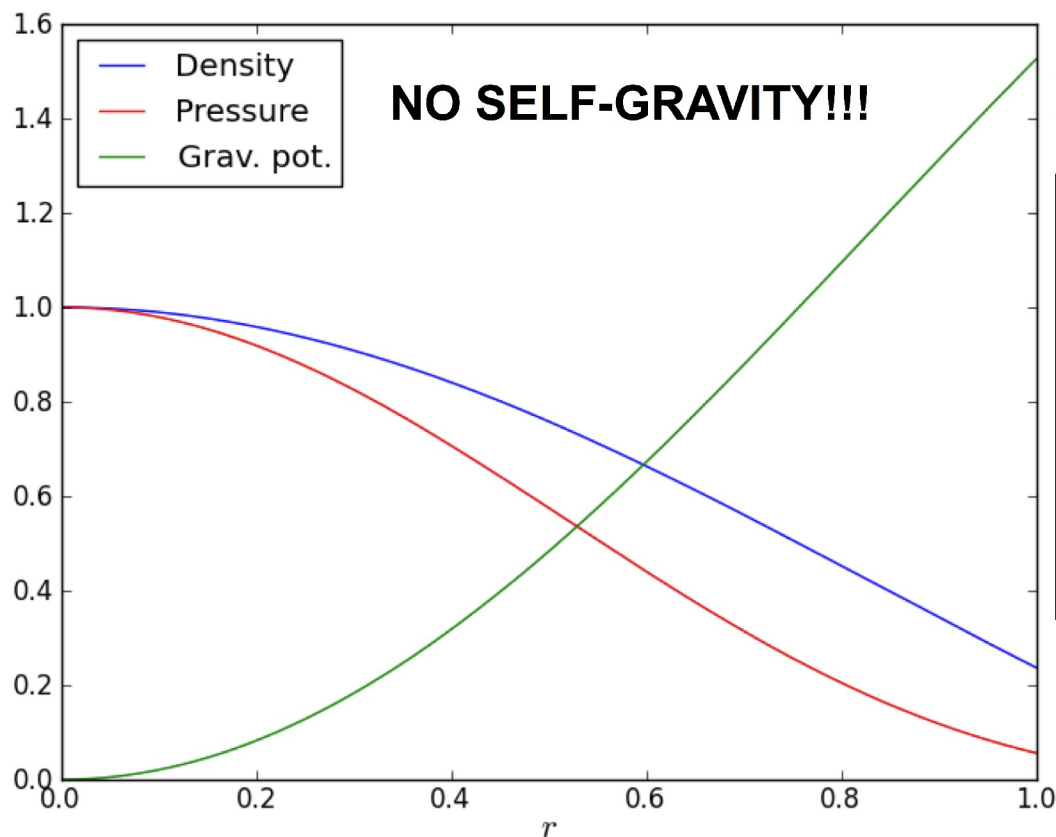
# Example 6 (2)

Polytrope: model star  $\gamma = 2 \sim$  neutron stars

$$\text{HSE: } \frac{p_{i+1} - p_i}{\Delta r} = -\frac{\rho_i + \rho_{i+1}}{2} \frac{GM_{1+1/2}}{r_{i+1/2}^2} \quad \text{Poisson: } \frac{\phi_{i+1} - \phi_i}{\Delta r} = \frac{GM_{1+1/2}}{r_{i+1/2}^2}$$

$$p_i = K_i \rho_i^\gamma \quad K = \text{const.}$$

$$M_{i+1/2} = \int_0^{r_{i+1/2}} 4\pi r^2 dr$$



Error in pressure:

N	1st	2ndTVD
32	2.3E-02 / <b>2.7E-16</b>	1.8E-03 / <b>1.4E-16</b>
64	1.1E-02 / <b>5.7E-16</b>	4.4E-04 / <b>5.0E-16</b>
128	5.7E-03 / <b>4.3E-16</b>	1.1E-04 / <b>3.3E-16</b>
256	2.8E-03 / <b>1.0E-15</b>	2.8E-05 / <b>7.7E-16</b>
512	1.4E-03 / <b>6.6E-13</b>	6.9E-06 / <b>3.5E-16</b>

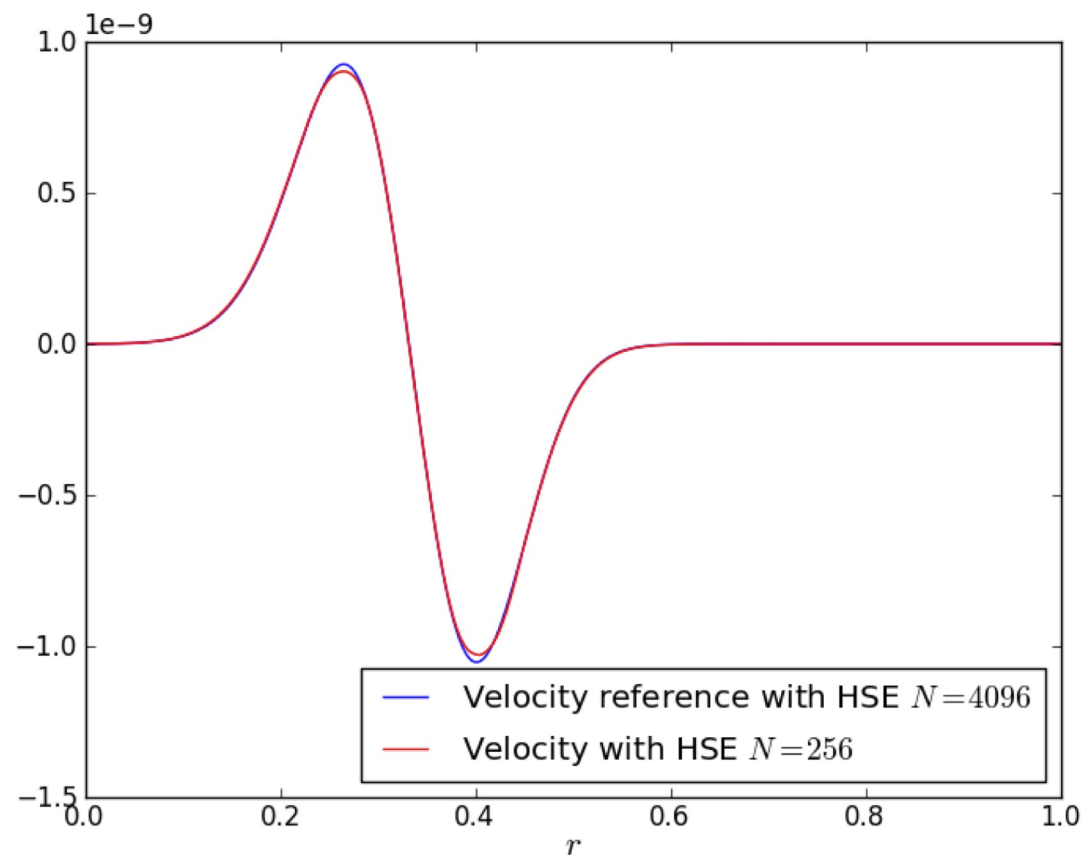
$$Err = \frac{1}{N} \sum_i |p_i - p_i^0|$$

# Example 6 (3)

Polytrope: model star  $\gamma = 2$  ~ neutron stars

+ density perturbation

$$\rho(r) = \rho(r) \left(1 + 10^{-6} \exp(-100r^2)\right)$$



Without HSE  
reconstruction the  
velocity is way off!

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# Multi-dimensional extension

- Straight forward directional application of HydroStatic Reconstruction

$$\frac{d\mathbf{u}_{i,j}}{dt} = \mathbf{L}(\mathbf{u}) = -\frac{1}{\Delta x} (\mathbf{F}_{i+1/2,j} - \mathbf{F}_{i-1/2,j}) - \frac{1}{\Delta y} (\mathbf{G}_{i,j+1/2} - \mathbf{G}_{i,j-1/2}) + \mathbf{S}_{i,j}$$

- Numerical equilibrium:

$$\frac{p_{i+1,j} - p_{i,j}}{\Delta x} = -\frac{\rho_{i,j} + \rho_{i+1,j}}{2} \frac{\phi_{i+1,j} - \phi_{i,j}}{\Delta x}$$
$$\frac{p_{i,j+1} - p_{i,j}}{\Delta y} = -\frac{\rho_{i,j} + \rho_{i,j+1}}{2} \frac{\phi_{i,j+1} - \phi_{i,j}}{\Delta y}$$

**3D analogous...**



# Example 7

Polytrope: model star (e.g. main sequence stars, white dwarfs, neutron stars)

HSE:  $\nabla p = -\rho \nabla \phi$  Poisson equation:  $\nabla^2 \phi = -4\pi G \rho$

Equation of state  $p = K \rho^\gamma$   $K = 1$

Take  $\gamma = 2$  ~ neutron stars

Then there's an exact solution:  $\rho(\mathbf{x}) = \rho_c \frac{\sin(\alpha r)}{r}$

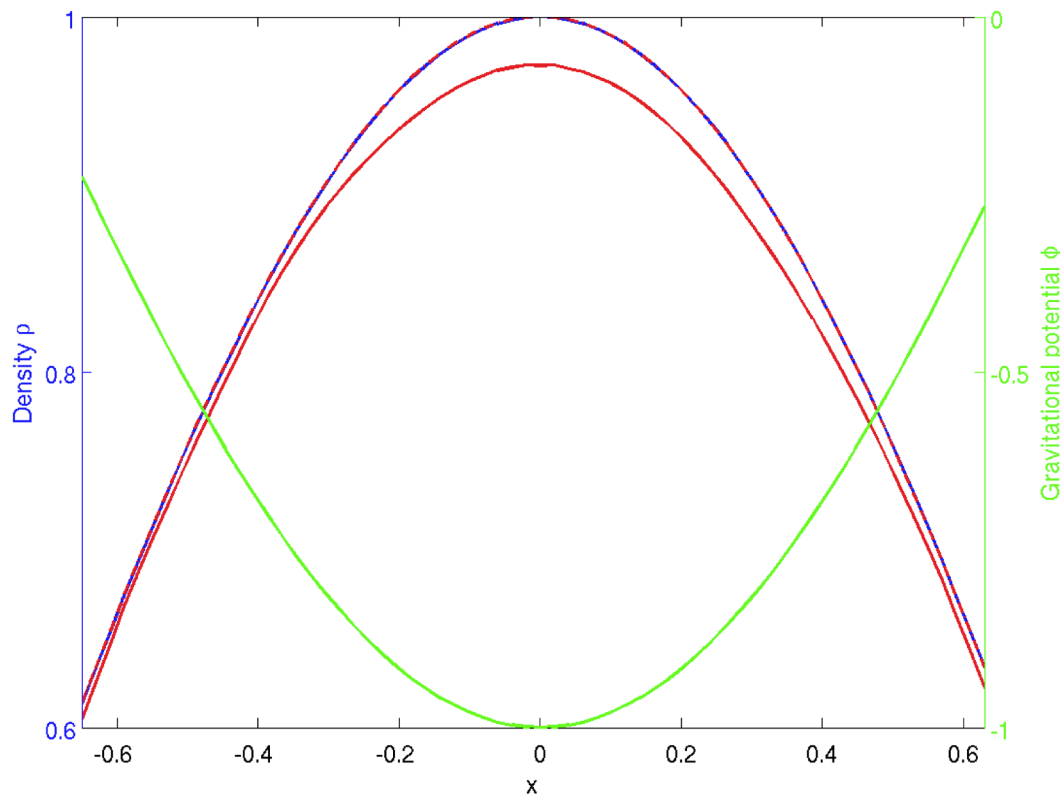
Central density

$$\phi(\mathbf{x}) = -\gamma K \rho(\mathbf{x})$$

$$\alpha = \sqrt{\frac{2K}{4\pi G}} \quad r = \sqrt{x^2 + y^2 + z^2}$$

# Example 7

Evolution for 20 “sound crossing” times



— NO HSE  
 - - - WITH HSE  
 — Reference

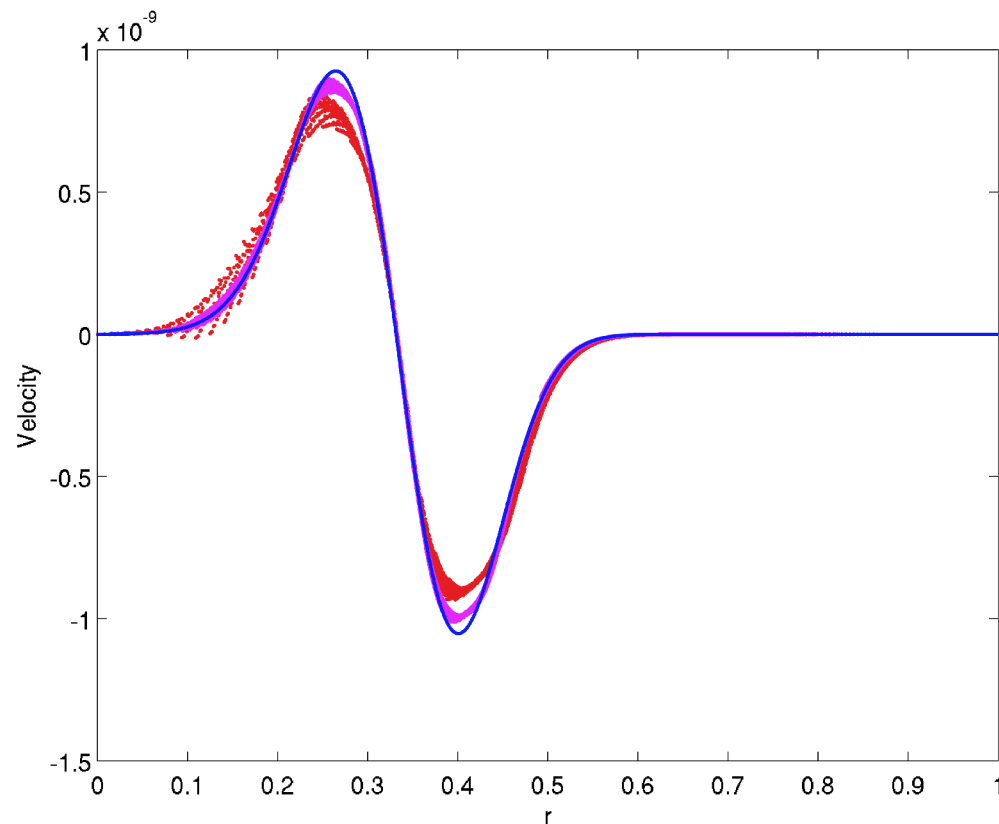
Error in density:

N	2ndTVD
64	1.9E-02 / <b>1.2E-15</b>
128	4.9E-03 / <b>3.4E-15</b>

$$Err = \frac{1}{N} \sum_i |\rho_i - \rho_i^0|$$

# Example 7

(Central) density perturbation



Without HSE  
reconstruction the  
velocity is way off!

$\rho$

# Conclusions

- 1D well-balanced scheme for hydrostatic equilibrium (for any Equation of State EoS)
- Extension to higher-order? Non-zero velocity steady state?
- Multi-D well-balanced scheme for hydrostatic equilibrium
  - Unfortunately with limitations (so far...)  
Although not exactly well-balanced for general EoS, the ability to maintain HSE is greatly increased

**Thank you for you attention!!!**