A WENO/TVD scheme for the approximation of atmospheric phenomena

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Framework

This talk deals with the numerical approximation of two-dimensional systems of balance laws of the form

$$\partial_{t}\,Q\,+\,\partial_{x}\,\,\mathcal{F}\left(Q
ight)+\,\partial_{z}\,\,\mathcal{H}\left(Q
ight)=\,\mathcal{S}\left(Q
ight).$$

The source term is treated via splitting: we solve an advection step

$$\partial_{t} Q + \partial_{x} \mathcal{F}(Q) + \partial_{z} \mathcal{H}(Q) = 0,$$

to be combined with a procedure for the resolution of the source term dynamics

$$\partial_t(Q) = \mathcal{S}(Q).$$

Framework

Ideally, schemes should be:

- Accurate.
- Robust.
- As efficient as possible.

Some schemes in the context of this talk:

- WENO schemes: data reconstruction + low-order flux.
- TVD schemes: monotonicity constraints over reconstructed data.
- WENO/TVD schemes: coherent interaction between non-oscillatory fluxes and high-order reconstructions.

Outline

The WENO-TVD scheme

- High-order of accuracy in space
- Numerical fluxes
- High-order of accuracy in time

2 Numerical tests

- 2D advection
- 2D convective tests
- A 2.5D layered model

Final remarks



The WENO-TVD scheme

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A semi-discrete approach

Averaging in space inside every control volume leads to

Semi-discrete system

$$rac{dQ_{i,j}(t)}{dt} = -rac{1}{\Delta x}(F_{i+1/2,j}-F_{i-1/2,j}) - rac{1}{\Delta z}(H_{i,j+1/2}-H_{i,j-1/2})\,,$$

where

$$Q_{i,j} = rac{1}{\Delta x} rac{1}{\Delta z} \int_{x_{i-1/2}}^{x_{i+1/2}} \int_{z_{j-1/2}}^{z_{j+1/2}} Q(x,z,t) \, dz \, dx,$$

$$egin{aligned} F_{i+1/2,j} &= rac{1}{\Delta z} \int_{z_{j-1/2}}^{z_{j+1/2}} \mathcal{F}(Q(x_{i+1/2},z,t)) \, dz \, , \ H_{i,j+1/2} &= rac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \mathcal{H}(Q(x,z_{j+1/2},t)) \, dx \, . \end{aligned}$$

Approximated formulation

We approximate the fluxes by conventional Gaussian quadrature formulas

In order to compute flux calculations we want:

- High-order accurate values for Q at Gauss points.
- A proper definition of the numerical fluxes F and H.

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The high-order in space scheme

Increasing accuracy in space: WENO interpolation

- Generates one polynomial of degree r per volume, $p_i^r(x) = v(x) + O(\delta x^{r+1}).$
- Conservative with respect to the cell averages

$$rac{1}{meas(Q_{\,i})}\int_{Q_{\,i}}p_i^r(x)\,dx=V_i$$
 .

• Keeps control of the oscillations by weighting according to smoothness indicators.

High-order interpolaton

From [Balsara et al., Journal of Computational Physics, 2007, 2009].

2D WENO reconstruction

In a 2D cartesian mesh, given a set of cell averages $\{q_{ij}\}$ we seek a local and minimal polynomial approximation:

$$egin{aligned} q_{ij}^r(\xi,\zeta) &= q_0 + q_x P_1(\xi) + q_z P_1(\zeta) & \longrightarrow & 2 ext{nd order} \ + q_{xx} P_2(\xi) + q_{zz} P_2(\zeta) + q_{xz} P_1(\xi) P_1(\zeta) & \longrightarrow & 3 ext{rd order} \ + q_{xxx} P_3(\xi) + q_{zzz} P_3(\zeta) \ + q_{xxz} P_2(\xi) P_1(\zeta) + q_{xzz} P_1(\xi) P_2(\zeta) & \longrightarrow & 4 ext{th order} \ P_1(x) &= x \,, \qquad P_2(x) = x^2 - rac{1}{12}. \end{aligned}$$

High-order interpolaton

2D WENO reconstruction

- We perform a 1D WENO in each direction in order to recover non-mixed terms.
- **2** We compute mixed terms with a lower resolution 2D stencils.
- We compute the 2D smoothness indicators and assign equal weights.

Numerical tests

2D stencils

Reconstruction in x-direction

$q_{i-1,j+1}$	$q_{i,j+1}$	$q_{i+1,j+1}$
$q_{i-1,j}$	$q_{i,j}$	$q_{i+1,j}$
$q_{i-1,j-1}$	$q_{i,j-1}$	$q_{i+1,j-1}$

2D stencils

Reconstruction in y-direction

$q_{i-1,j+1}$	$q_{i,j+1}$	$q_{i+1,j+1}$
$q_{i-1,j}$	$q_{i,j}$	$q_{i+1,j}$
$q_{i-1,j-1}$	$q_{i,j-1}$	$q_{i+1,j-1}$

1D reconstruction

1D stencils

$$S^1 = \{Q_{-2}, Q_{-1}, Q_0\}, \quad S^2 = \{Q_{-1}, Q_0, Q_1\}, \quad S^3 = \{Q_0, Q_1, Q_2\}.$$

Reconstructed polynomials

$$Q^{(i)}(x) = Q^{(i)}_0 + Q^{(i)}_x P_1(x) + Q^{(i)}_{xx} P_2(x) \qquad i=1,2,3.$$

The coefficients are given by

$$\begin{split} S^{1} &: \quad Q_{x}^{(1)} = \frac{-4Q_{-1} + Q_{-2} + 3Q_{0}}{2}, \ Q_{xx}^{(1)} = \frac{Q_{-2} - 2Q_{-1} + Q_{0}}{2}, \\ S^{2} &: \quad Q_{x}^{(2)} = \frac{Q_{1} - Q_{-1}}{2}, \ Q_{xx}^{(2)} = \frac{Q_{-1} - 2Q_{0} + Q_{1}}{2}, \\ S^{3} &: \quad Q_{x}^{(3)} = \frac{-3Q_{0} + 4Q_{1} - Q_{2}}{2}, \ Q_{xx}^{(3)} = \frac{Q_{0} - 2Q_{-1} + Q_{2}}{2}. \end{split}$$

.

1D reconstruction

Smoothness indicators

$$IS^{(i)} = \left(Q_x^{(i)}\right)^2 + \frac{13}{3} \left(Q_{xx}^{(i)}\right)^2$$

WENO weights

$$\omega^{(i)} = \frac{\alpha^{(i)}}{\sum_{i=1}^{3} \alpha^{(i)}}, \quad \alpha^{(i)} = \frac{\lambda^{(i)}}{(\epsilon + IS^{(i)})^r},$$

 $\epsilon = 10^{-12}$, r = 5, $\lambda^{(1)} = \lambda^{(3)} = 1$, while $\lambda^{(2)} = 100$. The 1D reconstructed polynomial is given by

$$Q(x) = \omega^{(1)}Q^{(1)}(x) + \omega^{(2)}Q^{(2)}(x) + \omega^{(3)}Q^{(3)}(x).$$

2D stencils

1st stencil for the computation of q_{xy}

$q_{i-1,j+1}$	$q_{i,j+1}$	$q_{i+1,j+1}$
$q_{i-1,j}$	$q_{i,j}$	$q_{i+1,j}$
$q_{i-1,j-1}$	$q_{i,j-1}$	$q_{i+1,j-1}$

2D stencils

2nd stencil for the computation of q_{xy}

$q_{i-1,j+1}$	$q_{i,j+1}$	$q_{i+1,j+1}$
$q_{i-1,j}$	$q_{i,j}$	$q_{i+1,j}$
$q_{i-1,j-1}$	$q_{i,j-1}$	$q_{i+1,j-1}$

2D stencils

3rd stencil for the computation of q_{xy}

$q_{i-1,j+1}$	$q_{i,j+1}$	$q_{i+1,j+1}$
$q_{i-1,j}$	$q_{i,j}$	$q_{i+1,j}$
$q_{i-1,j-1}$	$q_{i,j-1}$	$q_{i+1,j-1}$

2D stencils

4ht stencil for the computation of q_{xy}

$q_{i-1,j+1}$	$q_{i,j+1}$	$q_{i+1,j+1}$
$q_{i-1,j}$	$q_{i,j}$	$q_{i+1,j}$
$q_{i-1,j-1}$	$q_{i,j-1}$	$q_{i+1,j-1}$

Mixed terms for 2D reconstruction

Cross-term formulas

The corresponding smoothness indicators are given by

$$IS^{(i)} = 4 \left(Q_{xx}^{(i)}\right)^2 + 4 \left(Q_{zz}^{(i)}\right)^2 + \left(Q_{xz}^{(i)}\right)^2.$$

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Numerical fluxes

FLIC approach

$$\begin{split} F_{i+1/2,j}^{FLIC} &= F_{i+1/2,j}^{FORCE} + \psi_{i+1/2,j} \left(F_{i+1/2,j}^{LW} - F_{i+1/2,j}^{FORCE} \right), \\ F_{i+1/2,j}^{FORCE} &= \frac{1}{2} \left(F_{i+1/2,j}^{LW} + F_{i+1/2,j}^{LF} \right), \\ F_{i+1/2,j}^{LF} &= \frac{1}{2} \left(\mathcal{F} \left(Q_{i+1/2,j}^L \right) + \mathcal{F} \left(Q_{i+1/2,j}^R \right) \right), \\ &\quad - \frac{1}{4} \frac{\Delta x}{\Delta t} \left(Q_{i+1/2,j}^R - Q_{i+1/2,j}^L \right), \\ F_{i+1/2,j}^{LW} &= \mathcal{F} \left(Q_{i+1/2,j}^* + Q_{i+1/2,j}^R \right) \\ &\quad Q_{i+1/2,j}^* &= \frac{1}{2} \left(Q_{i+1/2,j}^L + Q_{i+1/2,j}^R \right) \\ &\quad - \frac{\Delta t}{\Delta x} \left(\mathcal{F} \left(Q_{i+1/2,j}^R \right) - \mathcal{F} \left(Q_{i+1/2,j}^L \right) \right). \end{split}$$

Limiters

The function $\psi_{i+1/2,j} = \psi_{i+1/2,j}(r^L_{i+1/2,j},r^R_{i+1/2,j})$ is a flux limiter.

Flux limiters

SUPERBEE:

$$\psi(r) = egin{cases} 0 & ext{if } r \leq 0, \ 2r & ext{if } 0 \leq r \leq rac{1}{2}, \ 1 & ext{if } rac{1}{2} \leq r \leq 1, \ \min\left\{2, \phi_g + (1-\phi_g)r
ight\} & ext{if } r \geq 1, \ \phi_g = rac{1-|c|}{1+|c|}, \ \phi_g = rac{1-|c|}{1+|c|}, \ e^R & e^R = e^L \end{array}$$

$$r_{i+1/2,j}^L = rac{e_{i-1/2,j}^R - e_{i-1/2,j}^L}{e_{i+1/2,j}^R - e_{i+1/2,j}^L}, \qquad r_{i+1/2,j}^R = rac{e_{i+3/2,j}^R - e_{i+3/2,j}^L}{e_{i+1/2,j}^R - e_{i+1/2,j}^L},
onumber \ \psi_{i+1/2,j} = \min(\psi(r_{i+1/2,j}^L), \psi(r_{i+1/2,j}^R)).$$

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Final remarks



Moving forward in time

At a given starting time t^n , we begin by considering the semi-discrete scheme

$$\frac{dQ_{i,j}(t)}{dt} = L_{i,j}(Q),$$

3rd order TVD Runge-Kutta scheme

$$\begin{aligned} & \mathcal{Q}_{i,j}^{n+\frac{1}{3}} &= \mathcal{Q}_{i,j}^{n} + \Delta t \, L_{i,j}(\mathcal{Q}_{i,j}^{n}), \\ & \mathcal{Q}_{i,j}^{n+\frac{2}{3}} &= \frac{3}{4} \mathcal{Q}_{i,j}^{n} + \frac{1}{4} \mathcal{Q}_{i,j}^{n+\frac{1}{3}} + \frac{1}{4} \Delta t \, L_{i,j}(\mathcal{Q}_{i,j}^{n+\frac{1}{3}}), \\ & \mathcal{Q}_{i,j}^{n+1} &= \frac{1}{3} \mathcal{Q}_{i,j}^{n} + \frac{2}{3} \mathcal{Q}_{i,j}^{n+\frac{2}{3}} + \frac{2}{3} \Delta t \, L_{i,j}(\mathcal{Q}_{i,j}^{n+\frac{2}{3}}). \end{aligned}$$

High-order of accuracy in time





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Doswell frontogenesis: setting

We set the domain $\Omega = [-5,\,5]^2,$ and an advection model given by

$$\partial_t \, Q \, + \, \partial_x \left(a Q
ight) + \, \partial_z \left(b Q
ight) = 0 \ ,$$

with

$$a = -zf(r), \quad b = xf(r), \quad f(r) = rac{1}{r}v(r), \quad v(r) = ar{v}\, sech^2(r)\, tanh(r),$$

 $r = \sqrt{x^2 + z^2}, \quad ar{v} = 2.59807.$

The initial condition for this test is given by

$$Q(x,z,0)=tanh\left(rac{z}{\delta}
ight),$$

generating the following exact solution

$$Q(x,z,t) = tanh\left(rac{z\cos(vt)-x\sin(vt)}{\delta}
ight)$$

Numerical tests

Doswell frontogenesis: results

Evolution for a sharp front

Doswell frontogenesis: results

At t = 4[s], for $\delta = 10^{-6}$ and 200×200 elements.



The WENO-TVD scheme 000000000000 000 000

Doswell frontogenesis: results

At t = 4[s], for $\delta = 1$ and 200×200 elements.



Numerical tests

Doswell frontogenesis

Convergence rates at t = 4 [s], with $\delta = 1$.

Ν	L_∞ error	L_∞ order	L_1 error	L_1 order
50	3.4786e-001		1.2719e-002	
100	1.1140e-001	1.6	3.5136e-003	1.9
200	3.3302e-002	1.8	7.3045e-004	2.3
400	5.47780e-003	2.6	1.0541e-004	2.8

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The 2D Euler equations

Once the performance of the scheme for space-dependent advection has been assessed, we proceed with further testing for the set of 2D Euler equations

$$\partial_t\,Q\,+\,\partial_x\,\,\mathcal{F}\,+\,\partial_z\,\,\mathcal{H}\,=\,\mathcal{S}\,,$$

where

$$Q = \left[egin{array}{c}
ho u \
ho u \
ho w \
ho w \
ho
ho w \
ho
ho w \
ho
ho w \
ho w
ho
ho \end{array}
ight], \, \mathcal{F} = \left[egin{array}{c}
ho u \
ho u \
ho \mu w \
ho w \
ho w \
ho w \
ho w
ho \end{array}
ight], \, \mathcal{H} = \left[egin{array}{c}
ho w \
ho w \
ho w u \
ho w u \
ho w
ho \
ho w
ho \end{array}
ight], \, \mathcal{S} = -
ho g \hat{k}.$$

The 2D Euler equations

The system is closed by the equation of state for an ideal gas

$${\cal P} \ = C_0(
ho heta)^\gamma, \qquad C_0 = {R_d^\gamma\over {\cal P}_0^{-R_d/c_v}}.$$

Additionally, by defining the Exner pressure π

$$\pi \equiv \left(rac{\mathcal{P}}{\mathcal{P}_0}
ight)^{R/c_p}$$

•

the expression for the total energy of the system is given by

$$e = E_{Int} + E_{Kin} + E_{Pot} = c_v heta \pi + rac{1}{2}(u^2 + w^2) + gz$$
 .

Convective bubble in a neutral atmosphere: setting

The domain is $\Omega = [-10000, 10000] \times [0, 10000]$, with $\Delta x = \Delta z = 125 [m]$ and the potential temperature perturbation is given by

$$heta' = egin{cases} 2\cos\left(rac{\pi L}{2}
ight) & L \leq 1, \ 0 & i.o.c. \end{cases}, \quad L = rac{1}{2000}\sqrt{x^2 + (z-2000)^2}.$$

Simulation time has been set to 1000 [s], allowing the bubble to rise without hitting the top boundary; reflecting solid wall boundary conditions have been considered around the whole domain.

Convective bubble in a neutral atmosphere: results

Potential temperature, t = 0, with $\Delta x = \Delta z = 125$ [m]



Convective bubble in a neutral atmosphere: results

Potential temperature, t = 300, with $\Delta x = \Delta z = 125$ [m]



Convective bubble in a neutral atmosphere: results

Potential temperature, t = 600, with $\Delta x = \Delta z = 125$ [m]



Convective bubble in a neutral atmosphere: results

Potential temperature, t = 1000, with $\Delta x = \Delta z = 125$ [m]



Convective bubble in a neutral atmosphere: results

Normalized energy plot



Numerical tests

Density current: setting

In the domain $\Omega = [0, 20000] \times [0, 6000]$, with a system initially at rest, a cold bubble perturbation is added to the reference state,

$$heta' = egin{cases} -7.5\,(\cos{(\pi L)}+1) & L \leq 1, \ 0 & i.o.c. \end{cases}, \ L = \sqrt{\left(rac{x}{4000}
ight)^2 + \left(rac{z-2000}{2000}
ight)^2}$$

 Final remarks

Density current test case: results

Evolution of the perturbation, with $\Delta x = \Delta z = 125$ [m]

Density current: results

Final state after 15 min., $\Delta x = \Delta z = 200$, 100 and 50[m]



Density current: results

Normalized energy plot



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A 2.5D formulation for the Euler equations

• We consider a set of 3D Euler equations in flux form

 $\partial_t \, Q \,+\, \partial_x \,\, {\cal F} \,+\, \partial_y \,\, {\cal G} \,\,+\, \partial_z \,\, {\cal H} \,\,=\, {\cal S} \,\,.$

- We introduce 2 layers in the y-direction with a DG procedure.
- The interface fluxes in the y-direction is approximated taking into account upwind considerations.
- The dimensionally reduced, 2D system of balance laws

$$\partial_t Q_i + \partial_x \mathcal{F}_i + \partial_z \mathcal{H}_i = \mathcal{S}_i \quad i = 1, 2,$$

is approximated with the previously implemented WENO-TVD scheme.

Interaction between hot and cold bubbles: setting

We set $\Omega = [-10000, 10000] \times [-10000, 10000] \times [0, 10000]$, with $\Delta x = \Delta z = 125[m]$ and Δt chosen according to,

$$\Delta t = CFLrac{\Delta x}{\displaystyle \max_{i,j} \; (|vel-c_s|, |vel+c_s)|},$$

where CFL = 0.4, and u is initialized in both layers with a value of $20[ms^{-1}]$. A periodic boundary condition is set in the lateral *x*-direction while solid boundary walls are kept at the bottom and the top of the domain.

Interaction between hot and cold bubbles: setting

Temperatures in each layer are initialized in a different way:

$$heta_1=ar{ heta}_1+ heta_1', \quad heta_2=ar{ heta}_2+ heta_2',$$

with

$$\begin{split} \bar{\theta}_1 &= \bar{\theta}_2 = 300 [K], \\ \theta_1' &= \begin{cases} 10 \cos\left(\frac{\pi L}{2}\right) & L \leq 1, \\ 0 & i.o.c. \end{cases}, \quad L = \frac{1}{2000} \sqrt{x^2 + (z - 2000)^2}, \\ \theta_2' &= \begin{cases} -15 \cos\left(\frac{\pi L}{2}\right) & L \leq 1, \\ 0 & i.o.c. \end{cases}, \quad L = \frac{1}{2000} \sqrt{x^2 + (z - 8000)^2} \end{split}$$

Numerical tests

Hot and cold bubbles: results

Evolution in every layer

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Final comments

Outlook:

- 2D extension of a WENO/TVD scheme.
- Good qualitative and quantitative results in a class of specific problems.

Future research:

- High-order of accuracy.
- Adaptive combination of WENO-TVD.
- Efficiency issues.

Final comments

THANKS FOR YOU ATTENTION!

D. Kalise and I. Lie

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