

A dispersive property of the Euler-Korteweg system

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The Euler-Korteweg system consists of the following equations

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t u + (u \cdot \nabla)u + \nabla g_0(\rho) = \nabla (K(\rho)\Delta\rho + \frac{1}{2}K'(\rho)|\nabla\rho|^2), \end{cases} \quad (\text{EK})$$

It is a perturbation of the classical Euler equations, that takes into account the capillarity effects. The quantities involved are the density ρ and the velocity u , K is the so called Korteweg stress tensor.

On the opposite of the Navier-Stokes equations, the perturbation is *dispersive*.

The linearized system near a constant state $(\underline{u}, \underline{\rho})$ admits the following dispersion relation

$$(\tau + i\underline{u} \cdot \xi)^2 + \underline{\rho}(\underline{g}'|\xi|^2 + \underline{K}|\xi|^4) = 0.$$

At high frequencies it amounts to $\tau \sim \pm i\sqrt{\underline{K}\underline{\rho}}|\xi|^2$ and thus bears some similarity with the usual Schrödinger equation

$$i\partial_t u + a\Delta u = 0,$$

whose dispersion relation is $\tau + ia|\xi|^2 = 0$.

Local well-posedness of the Euler-Korteweg system in any dimension was obtained in 2007.

Theorem (Benzoni-Danchin-Descombes '07)

Given $s > d/2 + 1$, $u_0 \in H^s(\mathbb{R}^d)$, $\rho_0 \in C_b^0(\mathbb{R}^d)$ such that $\nabla \rho \in H^s$, there exists $T > 0$ and a unique solution $(\rho, u) \in C_T C_b \times C_T H^s$, $\nabla \rho \in C_T H^s$ of the Cauchy problem

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t u + (u \cdot \nabla) u + \nabla g_0(\rho) = \nabla (K(\rho) \Delta \rho + \frac{1}{2} K'(\rho) |\nabla \rho|^2), \\ (\rho, u)|_{t=0} = (\rho_0, u_0) \end{cases} \quad (1)$$

The proof relied on rather involved *a priori* estimates, for an extended (formally equivalent) system displaying a better structure :

$$\begin{cases} \partial_t \zeta + u \cdot \nabla \zeta + a(\zeta) \operatorname{div} u = 0, \\ \partial_t z + (u \cdot \nabla) z + i(\nabla z) \cdot w + i \nabla(a \operatorname{div} z) = -g'(\zeta) \operatorname{Re}(z). \end{cases} \quad (2)$$

where $\zeta = R(\rho)$, R is a primitive of the application $\rho \rightarrow \sqrt{K(\rho)/\rho}$,
 $w = \nabla \zeta$, $z = u + iw$, $a(\zeta) = \sqrt{R^{-1}(\zeta)K(R^{-1}(\zeta))}$.

The second equation actually looks like a *quasi-linear degenerate Schrödinger equation*.

Opposedly to the Schrödinger equation, no dispersive estimate was proved yet for the Euler-Korteweg system. Our main result is a local smoothing property.

Theorem

Under the assumptions of the local well-posedness theorem, if moreover u_0 is irrotational, the curves associated to the hamiltonian $a(x, 0)|\xi|^2$ are unbounded and $\nabla_{x,t}a(0, x) \leq C/(1 + |x|^2)$, then any solution $(u, \nabla\rho) \in (C_T H^s)^2$ additionally satisfies for some \tilde{T}

$$(u, \nabla\rho)/(1 + |x|) \in L^2([0, \tilde{T}]; H^{s+1/2}(\mathbb{R}^d)).$$

A few comments on the assumptions :

- the irrotationality seems natural since $\partial_t z + i\underline{a}\nabla\text{div}z = 0$ admits trivial stationary solution, which precisely correspond to “purely rotational” initial data, $\text{div}(z_0) = 0$.
- The second assumption means that the solutions of the differential equation

$$\begin{cases} X(t)' &= \nabla_{\xi}(a(X(t), 0)|\Xi(t)|^2) = 2a(X(t), 0)\Xi(t), \\ \Xi(t)' &= -\nabla_x(a(X(t), 0)|\Xi|^2), \end{cases}$$

satisfy $\lim_{t \rightarrow \infty} \|X(t)\| = +\infty$. It is standard in the frame of linear Schrödinger equations with variable coefficients.

Some elements of proof :

- Since the local gain of regularity is only of $1/2$ derivative, it can hardly be obtained by basic multiplier techniques. It is necessary to use slightly more sophisticated tools.
- Nonlinearities appear even in the highest order derivatives, thus the pseudo-differential calculus is not well-suited as it usually requires a lot of smoothness from the coefficients. A more fitted tool would be Bony's paradifferential calculus.

Para-differential calculus allows to replace a product uv by $T_u v + R(u, v)$, where R is (hopefully) smooth, and T_u acts $H^s \rightarrow H^s$. It is even possible for a class of symbol $s(x, \xi)$ that satisfy minimal regularity assumptions to define the paradifferential operators T_s .

A very basic sketch of proof : fix some symbol $p(x, \xi)$ and consider the derivative

$$\begin{aligned} \frac{d}{dt} \langle T_p z, z \rangle &= \langle T_p(-i\nabla a \operatorname{div} z), z \rangle + \langle T_p z, -i\nabla a \operatorname{div} z \rangle + \text{l.o.t.} \\ &= \langle [T_p, -i\nabla a \operatorname{div}] z, z \rangle + \text{l.o.t.} \end{aligned}$$

use then the rules of para-differential calculus and the irrotationality

$$\begin{aligned} \dots &= \langle [T_p, T_{-i|\xi|^2 a}] z, z \rangle + \text{l.o.t.} \\ &= \langle T_{\{ip, |\xi|^2 a\}} z, z \rangle + \text{l.o.t.} \end{aligned}$$

where $\{ip, |\xi|^2 a\}$ is the *Poisson bracket*

$$\sum_{j=1}^d \partial_{\xi_j} p \partial_{x_j} (a|\xi|^2) - \partial_{x_j} p \partial_{\xi_j} (a|\xi|^2).$$

We have obtained (roughly)

$$\frac{d}{dt} \langle T_p z, z \rangle \simeq \langle T_{\{ip, |\xi|^2 a\}} z, z \rangle.$$

If p is a zeroth order operator, and $\{ip, |\xi|^2 a\} \geq c|\xi|/(1 + |x|^2)$, it is then possible to use a Gårding-like inequality to deduce

$$\begin{aligned} \frac{d}{dt} \langle T_p z, z \rangle &\gtrsim c \|z / \sqrt{1 + |x|^2}\|_{H^{1/2}(\mathbb{R}^d)}^2 \\ \Rightarrow \int_0^{\tilde{T}} \|z(t) / \sqrt{1 + |x|^2}\|_{H^{1/2}}^2 dt &\lesssim \|z\|_{L^\infty([0, \tilde{T}], L^2(\mathbb{R}^d))}, \end{aligned}$$

which is the expected smoothing effect.

Why it is not *that* simple :

- The construction of p is complicated (but similar to the one of Doi for Schrödinger like equations),
- The Gårding inequality is not standard,
- The lower order terms are actually not neglectible,
- Instead of a gain $L^2 \rightarrow H^{1/2}$ we want a gain $H^s \rightarrow H^{s+1/2}$, thus instead of working on z one has to study the quantity $T_{|\xi|^s} z$, it raises new commutators and more “bad” lower order terms.

Some more details on the gauge method : set $Z_s = T_{\varphi|\xi|^s}z$, the equation satisfied by Z_s is

$$\partial_t Z_s + T_u \cdot \nabla Z_s + i(\nabla Z_s) \cdot w + i[\operatorname{div} \nabla, T_{\varphi|\xi|^s}]z - i \operatorname{div} T_a \nabla Z_s = l.o.t.$$

We have $i(\nabla Z_s) \cdot w \simeq T_{-w \cdot \xi |\xi|^s} \varphi z$, and $i[\operatorname{div} \nabla, T_{\varphi|\xi|^s}]z \simeq T_{\{a|\xi|^2, \varphi|\xi|^s\}}z$. To suppress the bad terms, it is sufficient to have

$$\{a|\xi|^2, \varphi|\xi|^s\} = \varphi|\xi|^s \xi \cdot w,$$

and the “miraculous” function $\varphi = \sqrt{\rho} a^{s/2}$ works (as in Benzoni-Danchin-Descombes) !

The Euler-Korteweg system admits traveling waves $(\underline{\rho}, \underline{u})$ that only depend on $x_1 - ct$, the assumptions for the smoothing effect are usually not satisfied even for the linearized equations near such waves :

$$\partial_t z + \underline{u} \nabla z + i \nabla z \cdot \underline{w} + i \nabla a \operatorname{div} z = l.o.t.$$

Nevertheless, it is still possible to prove local smoothing in special cases.

Proposition

Assume that

$$2\sqrt{a_0(x_1)} - \frac{a_0'(x_1)}{\sqrt{a_0(x_1)}} \geq \alpha > 0,$$

then the same local smoothing property is still true.

Principle of proof : Doi's construction of p does not work, but a simpler one is actually available. Essentially, local smoothing is reduced again to the positivity of $\{a|\xi|^2, p\}$, now the choice

$p = f(x_1 - ct) \frac{x \cdot \xi}{|\xi|}$ gives

$$\{a|\xi|^2, p\} = |\xi|(2af - x_1 a'f) + \frac{\xi_1 x \cdot \xi}{|\xi|} (a'f + 2f'a).$$

For $f = c/\sqrt{a}$ the bad term cancels, and the positivity condition becomes

$$\{a|\xi|^2, p\} = |\xi| \left(2\sqrt{a} - x_1 \frac{a'}{\sqrt{a}} \right) > 0,$$

which is precisely the assumption.

Thank you for you attention !